

CE 620: Finite Element Method, HW-3

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Notation: (i) n_{el} = number of elements and (ii) n_{en} = number of nodes per element.

1. Consider a heat conduction problem shown in Figure 1. The dimensions are in meters. The bar has a constant unit cross section, constant thermal conductivity $k = 5 \text{ W}^\circ\text{C}^{-1}\text{m}^{-1}$ and a linear heat source s as shown in Figure 1. The boundary conditions are $T(x = 1) = 100^\circ\text{C}$ and $T(x = 4) = 0^\circ\text{C}$. Divide the bar into two elements ($n_{el} = 2$) as shown in the Figure. Note that element 1 is a three-node (quadratic) element ($n_{en} = 3$), whereas element 2 is a two-node ($n_{en} = 2$) element.

- State the strong form representing the heat flow and solve it analytically. Find the temperature and flux distributions.
- Construct the element source matrices and assemble them to obtain the global source matrix. Note that the boundary flux matrix is zero.
- Find the temperature distribution using the FEM. Sketch the analytical (exact) and the finite element temperature distributions.
- Find the flux distribution using the FEM. Sketch the exact and the finite element flux distributions.

2. Given the one-dimensional elasticity problem as shown in Figure 2. The bar is constrained at both ends (A and C). Its cross-sectional area is constant ($A = 0.1 \text{ m}^2$) on segment AB and varies linearly $A = 0.05(x - 1)\text{m}^2$ on BC. The Young's modulus is $E = 2 \times 10^7 \text{ Pa}$. A distributed load $b = 10\text{Nm}^{-1}$ is applied along the left portion of the bar AB and point force $P = 150 \text{ N}$ acts at point B. The geometry, material properties, loads and boundary conditions are given in Figure 2a. Use a three-node element on AB ($n_{en} = 3$) and a two-node element on BC ($n_{en} = 2$) as shown in Figure 2b. The dimensions in Figure 2 are in meters.

- Construct the element body force matrices and assemble them to obtain the global force matrix.
- Construct the element stiffness matrices and assemble them to obtain the global stiffness matrix.
- Find and sketch the finite element displacements.
- Find and sketch the finite element stresses.

3. Consider a three-node quadratic element in one dimension with unequally spaced nodes as shown in Figure 3.

- Obtain the \mathbf{B}^e matrix.
- Consider an element with $x_1 = 0$, $x_2 = 1/4$ and $x_3 = 1$. Evaluate strain ϵ in terms of u_2 and u_3 ($u_1 = 0$).
- If you evaluate \mathbf{K}^e by one-point quadrature using $\mathbf{B}^{eT}\mathbf{E}^e\mathbf{A}^e\mathbf{B}^e$ for same coordinates as in (b) and constrain node 1 (i.e. $u_1 = 0$), is \mathbf{K}^e invertible? Assume EA to be constant over the element.
- If $u(x)$ in part (b) is given by $x_i^2/2$ at node- i , does it mean that $\epsilon = x$ for the given element?

Note on how to include point load in FEA.

Point load of magnitude P at a location x_0 on the body is in fact body force of the form $b(x) = P\delta(x - x_0)$, where $\delta(x - x_0)$ corresponds to Dirac-Delta function centered at location x_0 . Hence, the expression for weak form corresponding to the body force becomes

$$\int_0^L w(x)b(x)dx = \int_0^L w(x)P\delta(x - x_0)dx = Pw(x_0).$$

Since in FEA, $w(x) \approx w^h(x) = \langle w \rangle \{N(x)\}$, the quantity $w(x_0) \approx w^h(x_0) = \langle w \rangle \{N(x_0)\}$. Here $\{N(x)\}$ correspond to global shape functions at every node.

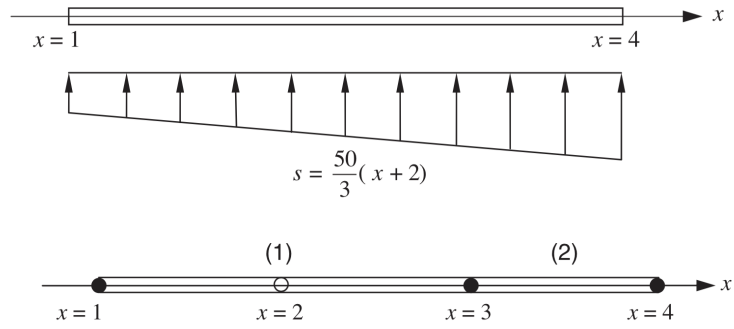


Figure 1: Heat conduction problem and its finite element mesh below.

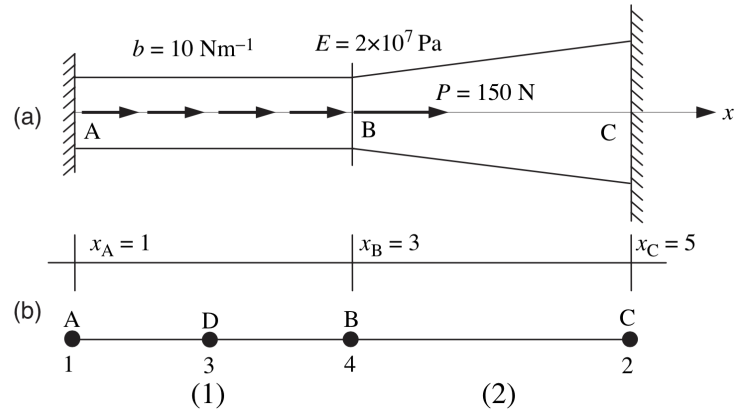


Figure 2: (a) Geometry, material properties, loads and boundary conditions for a bar with a variable cross-sectional area (b) the finite element model.

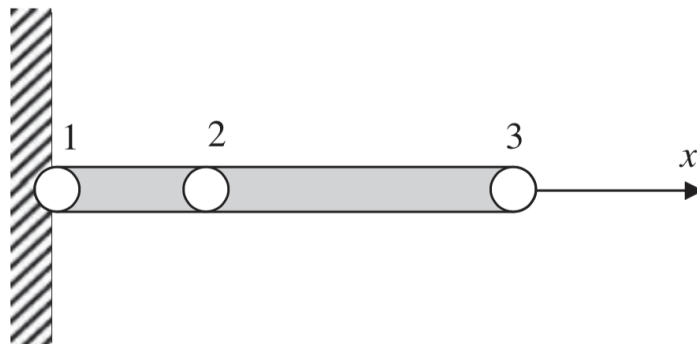


Figure 3: