

**Department Civil Engineering  
Indian Institute of Technology Bombay**

**CE 102 Engineering Mechanics: MID-SEMESTER EXAM**

Date: February 20, 2007

Time: 9:30 – 11:30 hours

Max. Marks: 30

**Note:** Answer all questions. Assume suitable data, if required, and state the same clearly.  
*Draw Free Body Diagram(s) clearly.*

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1. The mechanism shown in Fig. 1 is acted upon by the force  $P$ ; derive an expression for the magnitude of the force  $Q$  required to maintain the equilibrium. Collars  $C$  and  $D$  move on the horizontal rod without friction. (7.5)

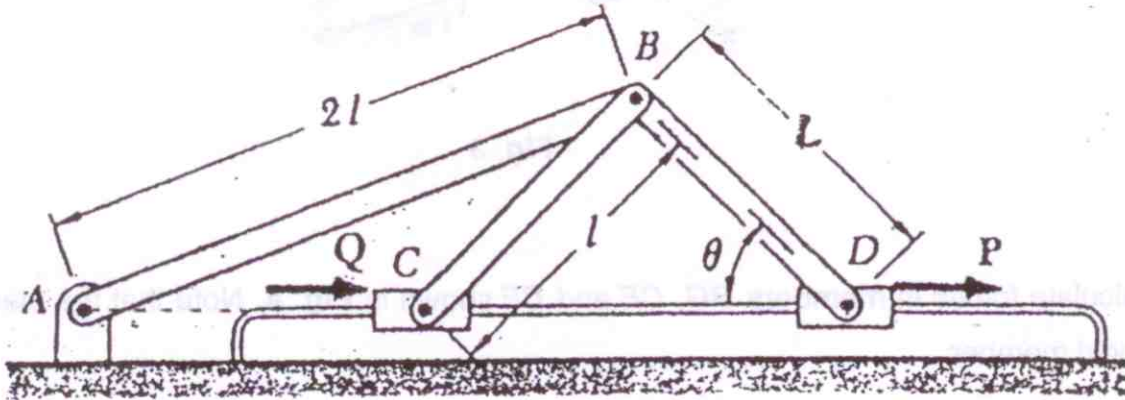


Fig. 1

2. Couple  $M$  is applied to pin  $B$  as shown in Fig. 2. Determine the reactions at the supports and the axial force in all the members (indicate tensile or compressive) when pin  $B$  is: (i) welded to  $AB$ , (ii) welded to  $BC$ . (7.5)

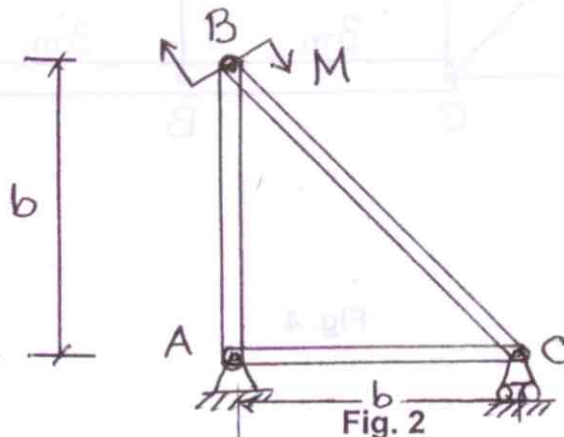


Fig. 2

3. The welded tubular frame shown in Fig. 3 is secured to the horizontal  $x$ - $y$  plane by a ball-and-socket joint at  $A$  and supported by a loose-fitting ring at  $B$ . Under the action of  $2\text{ kN}$  load, determine the tension in the cable  $CD$  and the reactions at the supports  $A$  and  $B$ . (7.5)

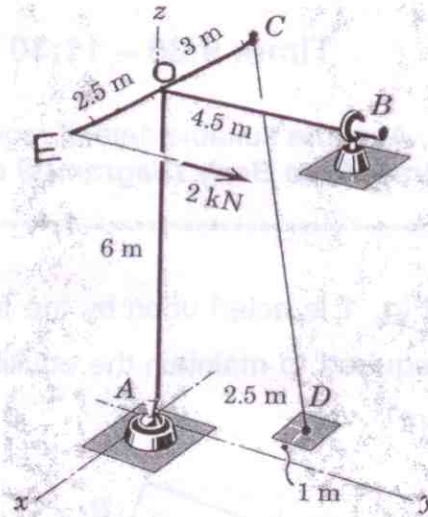


Fig. 3

4. Calculate forces in members  $BG$ ,  $CE$  and  $CF$  shown in Fig. 4. Note that the member  $ABC$  is a rigid member. (7.5)

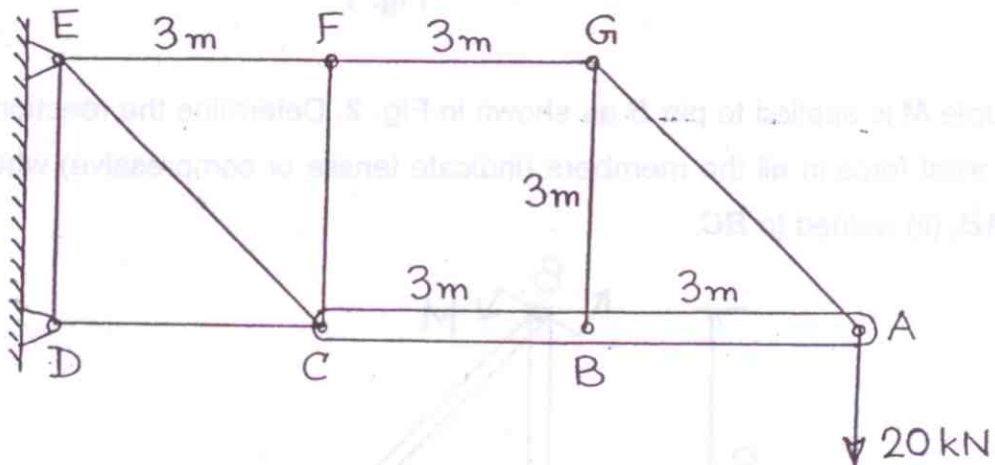
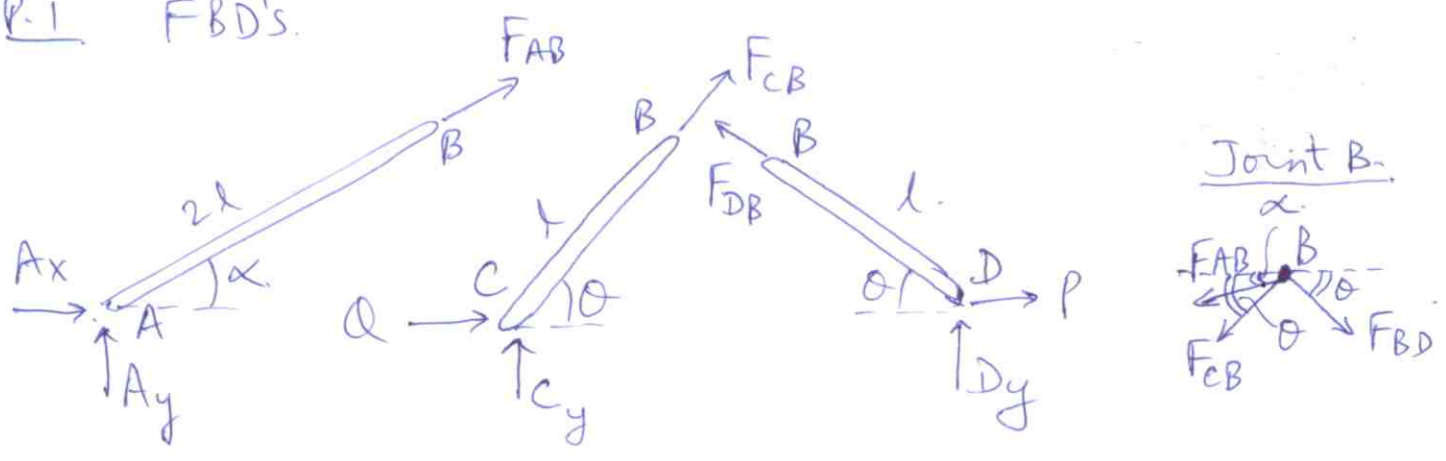


Fig. 4

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P.1 FBD's.



4 FBD's  $\rightarrow$  8 equations (force balance eqns)  $\rightarrow$  8 unknowns ( $A_x, A_y, F_{AB}, F_{CB}, F_{DB}, Q, C_y, D_y$ )  
 $\Rightarrow$  Statically Determinate.

FBD of DB:  $\sum F_x = 0 \Rightarrow F_{DB} \cos \theta = P \rightarrow$  ①

FBD of Joint B:  $\sum F_x = 0 \Rightarrow F_{DB} \cos \theta - F_{BA} \cos \alpha - F_{CB} \cos \theta = 0$  ②  
 $\sum F_y = 0 \Rightarrow F_{DB} \sin \theta + F_{BA} \sin \alpha + F_{CB} \sin \theta = 0$  ③

FBD of BC:  $\sum F_x = 0 \Rightarrow Q + F_{CB} \cos \theta = 0 \rightarrow$  ④

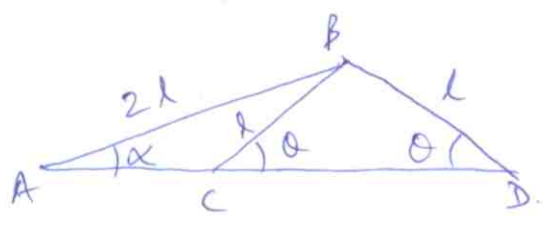
①-④ are 4 eqns in 4 unknowns.

Solution of ①-④:

②  $\times \sin \alpha$  + ③  $\times \cos \alpha = F_{DB} \sin(\alpha + \theta) - F_{CB} \sin(\alpha - \theta) = 0 \rightarrow$  ⑤

① & ⑤  $\rightarrow F_{CB} = F_{DB} \frac{\sin(\alpha + \theta)}{\sin(\alpha - \theta)} = \frac{P}{\cos \theta} \frac{\sin(\alpha + \theta)}{\sin(\alpha - \theta)} \rightarrow$  ⑥

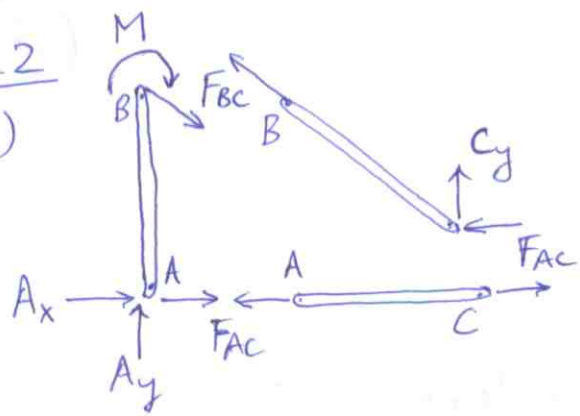
④ & ⑥  $\rightarrow Q = -F_{CB} \cos \theta = -P \frac{\sin(\alpha + \theta)}{\sin(\alpha - \theta)} = \frac{P \sin(\alpha + \theta)}{\sin(\theta - \alpha)}$



$\frac{\sin \alpha}{l} = \frac{\sin \theta}{2l} \Rightarrow \alpha = \sin^{-1} \left( \frac{1}{2} \sin \theta \right)$

$\theta > \alpha$ . So Q is true as shown in FBD.

P.2  
(i)



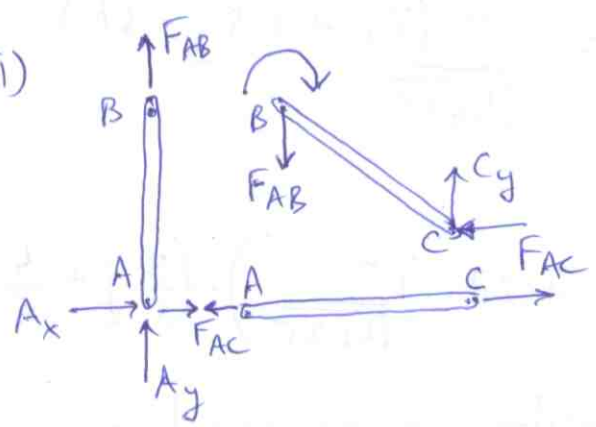
5 equations, 5 unknowns.

AB:  $\Sigma F_x: A_x + F_{AC} + F_{BC}/\sqrt{2} = 0 \rightarrow \textcircled{1}$   
 $\Sigma F_y: A_y - F_{BC}/\sqrt{2} = 0 \rightarrow \textcircled{2}$   
 $\Sigma M_A: M + \frac{F_{BC}}{\sqrt{2}} \cdot b = 0 \rightarrow \textcircled{3}$

BC:  $-F_{BC}/\sqrt{2} - F_{AC} = 0 \rightarrow \textcircled{4}$   
 $C_y + F_{BC}/\sqrt{2} = 0 \rightarrow \textcircled{5}$

Solution:  
 $F_{BC} = -\frac{\sqrt{2}M}{b} \leftarrow$   
 $A_y = -M/b$   
 $F_{AC} = M/b \leftarrow$   
 $C_y = M/b$   
 $A_x = 0$   
 $H_{AB} = -A_y = \frac{M}{b} \leftarrow$

(ii)



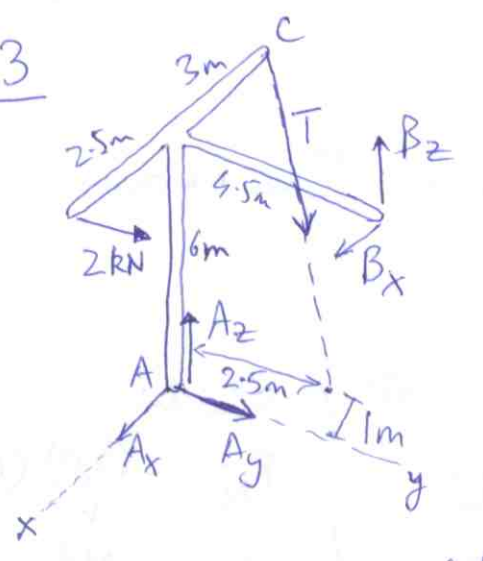
5 eqns, 5 unknowns.

BC:  $\Sigma M_C: -M + F_{AB} \cdot b = 0 \rightarrow \textcircled{6}$   
 $\Sigma F_x: -F_{AC} = 0 \rightarrow \textcircled{7}$   
 $\Sigma F_y: -F_{AB} + C_y = 0 \rightarrow \textcircled{8}$

AB:  $\Sigma F_y: F_{AB} + A_y = 0 \rightarrow \textcircled{9}$   
 $\Sigma F_x: A_x + F_{AC} = 0 \rightarrow \textcircled{10}$

Solution:  
 $F_{AB} = \frac{M}{b} \leftarrow$   
 $F_{AC} = 0 \leftarrow$   
 $C_y = \frac{M}{b}$   
 $A_y = -\frac{M}{b}$   
 $A_x = 0$   
 $H_{BC} = -\frac{F_{AB}}{\sqrt{2}} = -\frac{M}{b\sqrt{2}} \leftarrow$

P.3



Statically determinate 3-D problem. Unknowns are  $A_x, A_y, A_z, B_x, B_z, T$  (6).

$$\underline{e}_{AB} = \frac{4.5\mathbf{j} + 6\mathbf{k}}{\sqrt{4.5^2 + 6^2}} = \frac{3}{5}\mathbf{j} + \frac{4}{5}\mathbf{k} \quad (\text{unit vector along AB}).$$

Take moments about line AB to get T.

$$\sum M_{AB} = 0 : (2)(2.5)\mathbf{k} \cdot \underline{e}_{AB} + \underline{r}_{BC} \times \underline{T} \cdot \underline{e}_{AB} = 0$$

$$\underline{T} = \frac{(2\mathbf{i} + 2.5\mathbf{j} - 6\mathbf{k})T}{\sqrt{2^2 + 2.5^2 + 6^2}} = \frac{T(2\mathbf{i} + 2.5\mathbf{j} - 6\mathbf{k})}{\sqrt{46.25}}$$

$$\underline{r}_{BC} = -3\mathbf{i} - 4.5\mathbf{j}$$

$$\Rightarrow \left( 5\mathbf{k} + \frac{(-7.5\mathbf{k} - 18\mathbf{j} + 9\mathbf{k} + 27\mathbf{i})T}{\sqrt{46.25}} \right) \cdot \left( \frac{3}{5}\mathbf{j} + \frac{4}{5}\mathbf{k} \right) = 0$$

$$\frac{T}{\sqrt{46.25}} \left( -\frac{54}{5} + \frac{6}{5} \right) = -4 \Rightarrow \boxed{T = 2.8336 \text{ kN}}$$

Now take moments about x & z axes passing thru A to get  $B_x, B_z$

$$\sum M_{z\text{-axis}} = 0 : -4.5 B_x - \frac{2.5T}{\sqrt{46.25}}(3) + 2(2.5) = 0 \Rightarrow B_x = 0.4167 \text{ kN}$$

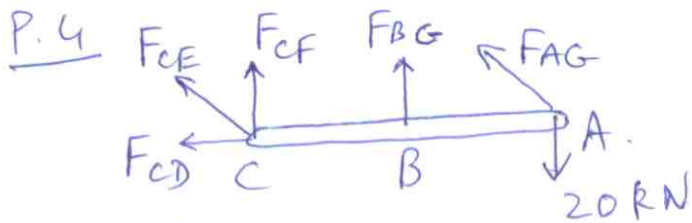
$$\sum M_{x\text{-axis}} = 0 : B_z(4.5) - 2(6) - \frac{2.5T}{\sqrt{46.25}}(6) = 0 \Rightarrow B_z = 4.0555 \text{ kN}$$

Sum forces in x, y, z directions to get  $A_x, A_y, A_z$ . (4)

$$\sum F_x: A_x + B_x + \frac{2T}{\sqrt{46.25}} = 0 \Rightarrow A_x = -1.25 \text{ kN} \leftarrow$$

$$\sum F_y: A_y + 2 + \frac{2.5T}{\sqrt{46.25}} = 0 \Rightarrow A_y = -3.0416 \text{ kN} \leftarrow$$

$$\sum F_z: A_z + B_z - \frac{6T}{\sqrt{46.25}} = 0 \Rightarrow A_z = -1.5555 \text{ kN} \leftarrow$$



FBD ABC:

$$\sum M_C = 0 \Rightarrow F_{BG}(3) - 20(6) + \frac{F_{AG}}{\sqrt{2}}(6) = 0 \rightarrow \textcircled{1}$$

FBD Joint G:

$$\sum F_y = 0 \Rightarrow \frac{F_{AG}}{\sqrt{2}} + F_{BG} = 0 \rightarrow \textcircled{2}$$

Solve  $\textcircled{1}, \textcircled{2} \rightarrow$

$$F_{BG} = -40 \text{ kN (compressive)} \leftarrow$$

$$F_{AG} = 40\sqrt{2} \text{ kN (T)}$$

FBD joint F:

$$\Rightarrow F_{CF} = 0 \leftarrow$$

FBD ABC:

$$\sum F_y = 0 \Rightarrow \frac{F_{CE}}{\sqrt{2}} + \cancel{F_{CF}} + \cancel{F_{BG} + \frac{F_{AG}}{\sqrt{2}}} - 20 = 0$$

$$\Rightarrow F_{CE} = 20\sqrt{2} \text{ kN (T)} \leftarrow$$