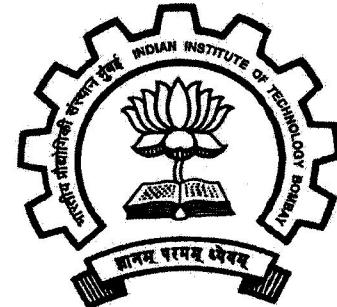


# PLANE PROBLEMS — 2 D

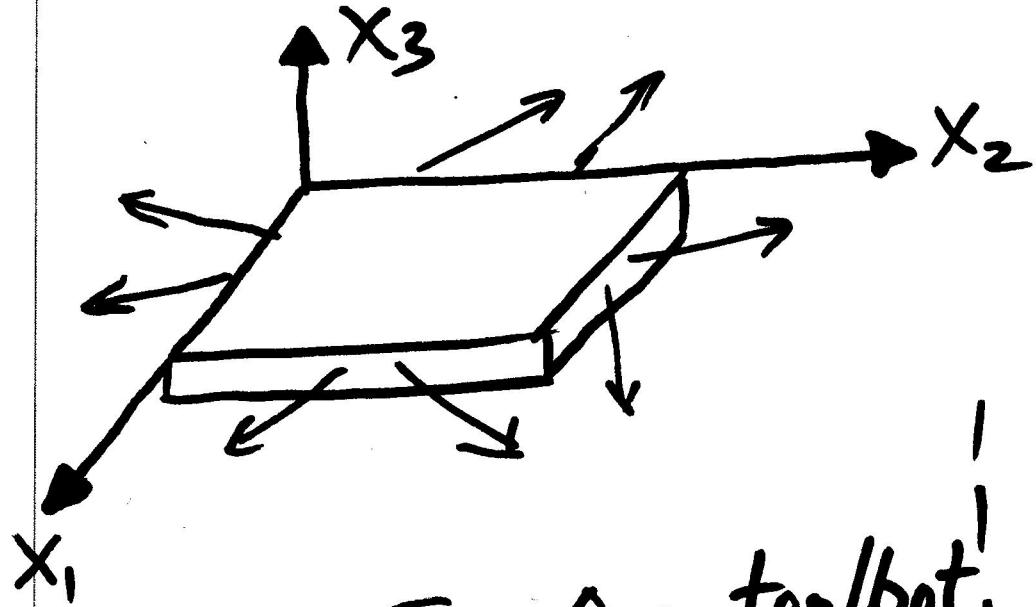
## ELASTICITY

- Plane Stress / Plane Strain.
- Airy Stress function
- Compatibility Eqn for plane stress / plane strain.



IIT Bombay

## PLANE STRESS

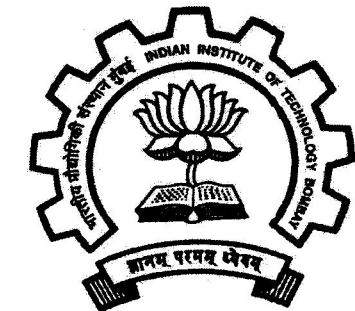


$x_1$   
BC's  $\Rightarrow \tau_{i3} = 0$  on top/bot face.

Thickness  $\Rightarrow \sigma_{i3} = 0$  throughout  
&  $\delta/\delta x_3 = 0$

$$\text{Equil : } \begin{aligned} \sigma_{11,1} + \sigma_{12,2} + f_1 &= 0 \rightarrow (A) \\ \sigma_{21,1} + \sigma_{22,2} + f_2 &= 0 \rightarrow (B) \end{aligned} \quad \begin{matrix} 3^{\text{rd}} \text{ eqn} \\ (\text{identity}) \end{matrix} \Rightarrow 0 = 0$$

- Thin plate
  - Loading in  $x_1 - x_2$  plane along thin edges.
  - No loading on top/bottom faces
  - Loading indep. of  $x_3$  coord.  
ie uniform in  $x_3$  direction.
  - $f_3 = 0$  (no b.f. in  $x_3$ -dir).



IIT Bombay

# Airy Stress function $\phi(x_1, x_2)$

Let  $f_1(x_1, x_2) = \psi_{,1}$ ;  $f_2(x_1, x_2) = \psi_{,2}$

$\psi(x_1, x_2) \rightarrow$  Body force Potential

(ie for conservative b.f.  $\underline{f} = \nabla \psi$ ).

Let  $\sigma_{11}(x_1, x_2) = \phi_{,22} - \psi$ ;  $\sigma_{22}(x_1, x_2) = \phi_{,11} - \psi$ ;  
 $\sigma_{12} = -\phi_{,12}$

$\phi(x_1, x_2) \rightarrow$  Airy Stress  $\underline{\underline{f}} \doteqdot$

$$\text{Equil: } \sigma_{11,1} + \sigma_{12,2} + f_1 = \phi_{,221} - \psi_{,1} - \phi_{,122} + \psi_{,1} = 0$$

$$\sigma_{21,1} + \sigma_{22,2} + f_2 = -\phi_{,121} + \phi_{,112} - \psi_{,2} + \psi_{,2} = 0$$

So Equil is identically satisfied (i.s.) if we recast problem in terms of  $\phi, \psi$ .



IIT Bombay

Thus instead of solving for  $\sigma_{11}, \sigma_{22}, \sigma_{12}$ , we solve for a single  $\phi(x_1, x_2)$ . How ??



IIT Bombay

# B.M. Compat Eqns:

$$\begin{matrix} i=1, \\ j=1 \end{matrix} : \nabla^2 \sigma_{11} + \frac{1}{1+\nu} (\sigma_{11,11} + \sigma_{22,11}) + 2f_{1,1} + \frac{\nu}{1-\nu} (f_{1,1} + f_{2,2}) = 0 \quad (I)$$

$$\begin{matrix} i=2 \\ j=2 \end{matrix} : \nabla^2 \sigma_{22} + \frac{1}{1+\nu} (\sigma_{11,22} + \sigma_{22,22}) + 2f_{2,2} + \frac{\nu}{1-\nu} (f_{1,1} + f_{2,2}) = 0 \quad (II)$$

$$\begin{matrix} i=1 \\ j=2 \end{matrix} : \nabla^2 \sigma_{12} + \frac{1}{1+\nu} (\sigma_{11,12} + \sigma_{22,12}) + f_{1,2} + f_{2,1} = 0 \quad (III)$$

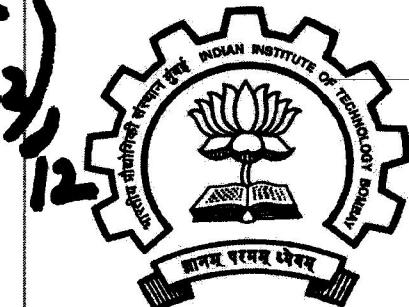
$$\begin{matrix} i=3 \\ j=3 \end{matrix} : \frac{\nu}{1-\nu} (f_{1,1} + f_{2,2}) = 0 \rightarrow (IV) \quad (IV)$$

$$\begin{matrix} i=1, j=3 \\ i=2, j=3 \end{matrix} \rightarrow 0=0 \rightarrow (V, VI)$$



IIT Bombay

From  $\frac{\partial(A)}{\partial x_2} + \frac{\partial(B)}{\partial x_1} = 0 = \nabla^2 \tau_{12} + (\tau_{11} + \tau_{22})$   
 equil,  $\frac{\partial}{\partial x_2}$        $\frac{\partial}{\partial x_1}$        $+ f_{1,2} + f_{2,1}$



IIT Bombay

$\Rightarrow$  III<sup>rd</sup> Compat violated if  $\nu \neq 0$   
 Also IV<sup>th</sup> Compat violated unless  $\underline{\underline{f_1}}, \underline{\underline{f_2}}$  const.  
 due to  $\partial/\partial x_3 = 0$  assumption  $\rightarrow$  (i)  
 So we cannot satisfy III, IV, compat.

$$\text{Compat (I) + (II)} \Rightarrow \nabla^2(\tau_{11} + \tau_{22}) = -\frac{2(1+\nu)}{(2+\nu)(1-\nu)}(f_{1,1} + f_{2,2})$$

Now Consider  $\underline{\underline{\text{Strain}}}$   $\underline{\underline{\text{Compat}}}^x$  (St Venants) eqns.

$$e_{11,22} + e_{22,11} = 2e_{12,12} \rightarrow ①; e_{33,11} = 0 \rightarrow ②$$

$$e_{33,22} = 0 \rightarrow ③; 0 = 0 \rightarrow ④, ⑤; e_{33,12} = 0 \rightarrow ⑥$$

Numbering  
as per table  
on p.6 of  
"Compatibility Eqn"

$$CL \rightarrow e_{11} = \frac{\sigma_{11}}{E} - \frac{\nu}{E} \sigma_{22}; \quad e_{22} = \frac{\sigma_{22}}{E} - \frac{\nu}{E} \sigma_{11}$$

$$e_{33} = -\frac{\nu}{E} (\sigma_{11} + \sigma_{22}), \quad e_{12} = \frac{1+\nu}{E} \sigma_{12}, \quad e_{13} = e_{23} = 0$$

$$CL \text{ in } ① \rightarrow \cancel{\frac{1}{E}} \left\{ (\sigma_{11} - \nu \sigma_{22})_{,22} + (\sigma_{22} - \nu \sigma_{11})_{,11} \right\} = \cancel{\frac{2(1+\nu)}{E}} \sigma_{12,12} \rightarrow *$$

$$\text{Equil} \rightarrow \frac{\partial(A)}{\partial x_1} + \frac{\partial(B)}{\partial x_2} = 0 = \sigma_{11,11} + \sigma_{22,22} + 2\sigma_{12,12} + f_{1,1} + f_{2,2} = 0$$

Eliminate  $\sigma_{12}$  from  $*$ ,  $**$   $\rightarrow \boxed{\nabla^2(\sigma_{11} + \sigma_{22}) = -(1+\nu) \nabla \cdot f \rightarrow (ii)}$

$$CL \text{ in } ② \rightarrow -\frac{\nu}{E} (\sigma_{11} + \sigma_{22})_{,11} = 0$$

$$\text{in } ③ \rightarrow -\frac{\nu}{E} (\sigma_{11} + \sigma_{22})_{,22} = 0$$

$$\text{in } ⑥ \rightarrow -\frac{\nu}{E} (\sigma_{11} + \sigma_{22})_{,12} = 0$$

$$\Rightarrow (\sigma_{11} + \sigma_{22}) = ax_1 + bx_2 + c$$

This places a severe restriction on  $\sigma_{11}$ ,  $\sigma_{22}$ ,  $e_{33}$   
which is unacceptable.

Hence ②, ③, ⑥ cannot be satisfied. (again due to  $\frac{\partial}{\partial x_3} = 0$ )



IIT Bombay

RHS of (i) & (ii) differ by factor, ie  

$$-\frac{2(1+\nu)}{(2+\nu)(1-\nu)}$$
 in (i) &  $-(1+\nu)$  in (ii). Why??



IIT Bombay

Strain Compat (St. Venant) & Stress Compat (BM) do not have one-to-one correspondence amongst the six eqns. Since some eqns in each set are non-satisfiable, we cannot expect the remaining eqn (ie (i) or (ii)) which we intend to satisfy to be identical.

Do we use (i) or (ii)??

(i) requires ignoring III, IV which in turn imply  $\nu = 0 \rightarrow$  this is a severe restriction on the solution.  
 (ii) requires  $(\sigma_{11} + \sigma_{22})$  to be linear f<sup>n</sup> of  $x_1, x_2$ . This is less severe restriction

So we choose Strain Compat (St. Venant) version ie (ii).

Subst  $\phi, \psi$  in Strain Compnt, Eq(ii)

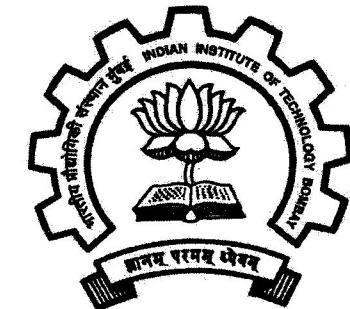
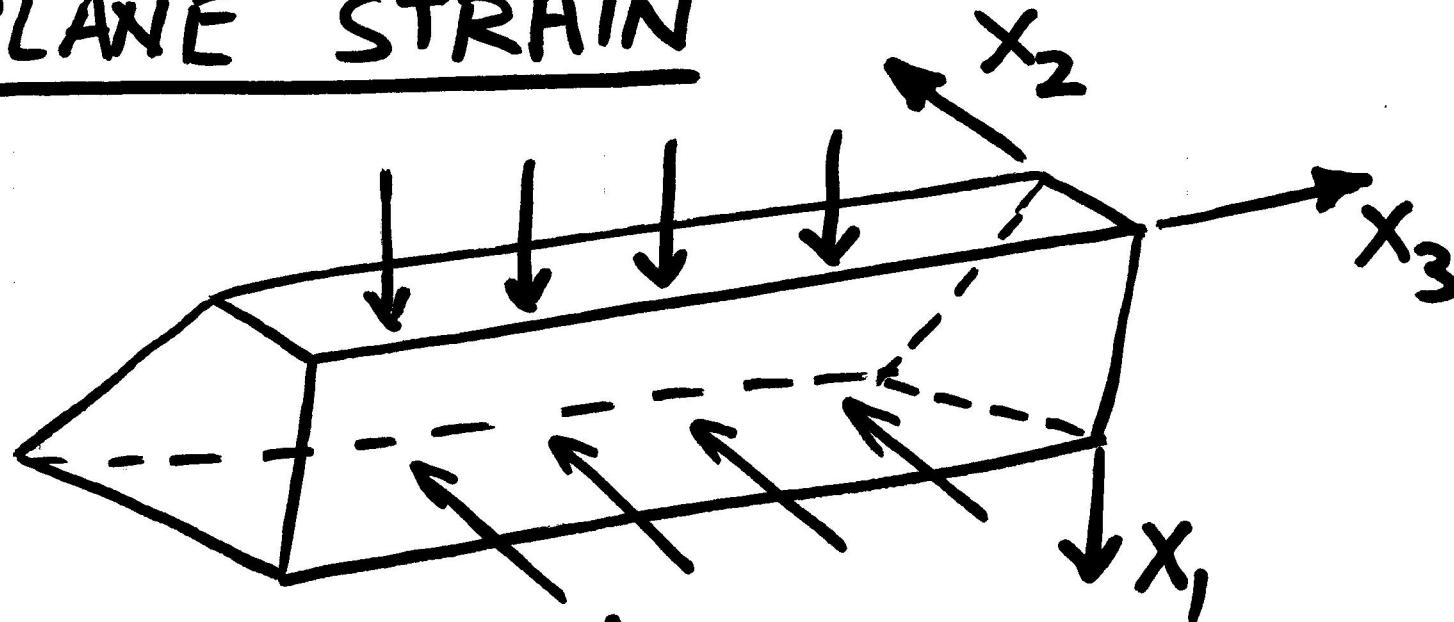
$$\nabla^2(\nabla^2\phi - 2\psi) = -(1+\nu)\nabla \cdot \nabla \psi = -(1+\nu)\nabla^2\psi$$

$$\boxed{\nabla^4\phi = (1-\nu)\nabla^2\psi}$$



IIT Bombay

# PLANE STRAIN



IIT Bombay

- Long Prismatic body.
- Load  $\perp$  ar to longitudinal axis, ie load has no  $x_3$  component.
- Load does not vary in long. dir. (ie  $x_3$  dir).
- Load restrained from long.
- Assume ends  $x_3=0, L$  displ., ie  $u_3=0$  at ends. Symmetry  $\Rightarrow u_3=0$  throughout ( $\div$  half,  $1/4, \dots$ ). So  $u_3(x_1, x_2, x_3)=0$

$$\therefore \frac{\partial(\text{load})}{\partial x_3} = 0 \rightarrow u_1, u_2, u_3 \stackrel{\sigma}{=} \text{indep of } x_3$$

ie  $\frac{\partial(\sigma)}{\partial x_3} = 0$



IIT Bombay

Example  $\rightarrow$  dam, retaining wall, pressure vessel

$$\therefore u_3 = 0, \frac{\partial}{\partial x_3} = 0 \rightarrow e_{13} = 0 \rightarrow \text{Plane strain.}$$

Get same equil eqns as on p.2.

STRAIN COMPAT Eqs: (St. Venant)

Eqs (2)-(6) i.e. (0=0). {ref. numbering scheme, p.6 of "Compat Eqn" notes}

$$\text{Eq (1)} \quad e_{11,22} + e_{22,11} = 2e_{12,12} \rightarrow \times$$

$$\text{C.L.} \rightarrow e_{33} = 0 \rightarrow \sigma_{33} = \nu(\sigma_{11} + \sigma_{22}) \rightarrow e_{11} = \frac{1-\nu^2}{E} (\sigma_{11} - \frac{\nu}{1-\nu} \sigma_{22})$$

subst CL in  $\times$

$$e_{22} = \frac{1-\nu^2}{E} (\sigma_{22} - \frac{\nu}{1-\nu} \sigma_{11})$$

Subst CL in  $\textcircled{*}$ ,

$$\frac{1-\nu^2}{E} \left[ \left( \sigma_{11} - \frac{\nu}{1-\nu} \sigma_{22} \right)_{,22} + \left( \sigma_{22} - \frac{\nu}{1-\nu} \sigma_{11} \right)_{,11} \right] = 2 \frac{(1+\nu)}{E} \sigma_{12,12}$$

Equil  $\rightarrow \frac{\partial A}{\partial x_1} + \frac{\partial B}{\partial x_2} \rightarrow -2\sigma_{12,12} = \sigma_{11,11} + \sigma_{22,22} + f_{1,1} + f_{2,2}$

Eliminate  $\sigma_{12,12}$  from compat above,

$$\nabla^2 (\sigma_{11} + \sigma_{22}) = -\frac{1}{1-\nu} \nabla \cdot \underline{f}$$

[ $\because$  all compat eqns satisfied, we expect Stress  
Compat (BM) eqns to yield identical result.]  
Subst Airy stress fn. & Body force potential,

$$\nabla^2 (\nabla^2 \phi - 2\psi) = -\frac{1}{1-\nu} \nabla \cdot \underline{\nabla \psi} = -\frac{1}{1-\nu} \nabla^2 \psi$$

$$\boxed{\nabla^4 \phi = \frac{1-2\nu}{1-\nu} \nabla^2 \psi}$$



IIT Bombay

## Hooke's Law :

## Plane Stress:

$$\sigma_{11} = \frac{E}{1+\nu} \left( e_{11} + \frac{\nu}{1-2\nu} [e_{11} + e_{22} + e_{33}] \right)$$



IIT Bombay

$$e_{33} = -\frac{\nu}{E}(\sigma_{11} + \sigma_{22}); \quad \epsilon_{11} = \frac{\sigma_{11} - \nu\sigma_{22}}{E}, \quad \epsilon_{22} = \frac{\sigma_{22} - \nu\sigma_{11}}{E}$$

$$\Rightarrow e_{33} = -\frac{\nu}{E} \frac{E}{1-\nu} (e_{11} + e_{22}) \Rightarrow \sigma_{11} = \frac{E}{1+\nu} \left( e_{11} + \frac{\nu}{1-\nu} (e_{11} + e_{22}) \right)$$

$$\sigma_{11} = \frac{E}{1-\nu^2} (\epsilon_{11} + \nu \epsilon_{22})$$

$$1 \quad \sigma_{22} = \frac{E}{1-\nu^2} (\epsilon_{22} + \nu \epsilon_{11})$$

$$\sigma_{12} = \frac{E}{1+\gamma} e_{12}$$

Plane strain :

$$\sigma_{11} = \frac{E}{1+\nu} \left[ e_{11} + \frac{\nu}{1-2\nu} (e_{11} + e_{22}) \right]$$

$$\sigma_{11} = \frac{E}{(1+\nu)(1-2\nu)} \left[ (1-\nu) e_{11} + \nu e_{22} \right]$$

$$\sigma_{22} = \frac{E}{(1+\nu)(1-2\nu)} \left[ (1-\nu) e_{22} + \nu e_{11} \right]$$

$$\sigma_{12} = \frac{E}{1+\nu} e_{12}; \quad \sigma_{33} = \frac{E}{(1+\nu)(1-2\nu)} \left[ \nu (e_{11} + e_{22}) \right]$$

$$\sigma_{33} = \nu (\sigma_{11} + \sigma_{22})$$

$$e_{11} = \frac{1}{E} \left[ (1-\nu^2) \sigma_{11} - \nu (1+\nu) \sigma_{22} \right], \quad e_{22} = \frac{1}{E} \left[ (1-\nu^2) \sigma_{22} - \nu (1+\nu) \sigma_{11} \right]$$

Plane stress  $\rightarrow$  Plane strain,  $E \rightarrow \frac{E}{1-\nu^2}$ ,  $\nu \rightarrow \frac{\nu}{1-\nu}$ , then drop "1"



IIT Bombay

# POLYNOMIAL SOLUTIONS of 2D Problems in Cartesian Coords

$\nabla^4 \phi = k \nabla^2 \psi$  (R depends on v,  
If b.f. due to gravity, diff for plane-stress/stain).

$$\psi = px + qy,$$

$$\Rightarrow \boxed{\nabla^4 \phi = 0} \rightarrow \text{Biharmonic eqn}$$

choose  $\phi = \sum_{N=1}^{\infty} \phi_N ; \phi_N = \sum_{i=0}^N A_{Ni} x^{N-i} y^i$

to satisfy Biharmonic.

$$\nabla^4 \phi_N = \sum_{i=0}^{N-4} B_{Ni} x^{(N-4-i)} y^i = 0$$

$$\Rightarrow B_{Ni} = 0, i=0 \dots N-4 \rightarrow \begin{matrix} \text{constraint eqns.} \\ \text{must be satisfied} \\ \text{for } N > 3 \end{matrix}$$



IIT Bombay



IIT Bombay

$$N=1: \phi_1 = a_1 x + b_1 y \rightarrow \nabla^4 \phi_1 = 0$$

$$\tau_{xx} = \tau_{yy} = -\phi, \quad \tau_{xy} = 0$$

$$N=2: \phi_2 = a_2 x^2 + b_2 xy + c_2 y^2 \rightarrow \nabla^4 \phi_2 = 0$$

$$\tau_{xx} = 2c_2, \quad \tau_{yy} = 2a_2, \quad \tau_{xy} = -b_2 \rightarrow \text{const} \stackrel{!}{=} -1 \text{ if } b.f = 0.$$

$$N=3: \phi_3 = a_3 x^3 + b_3 x^2 y + c_3 x y^2 + d_3 y^3$$

$$\nabla^4 \phi_3 = 0, \quad \left\{ \begin{array}{l} \tau_{xx} = 2(c_3 x + 3d_3 y); \quad \tau_{yy} = 2(b_3 y + 3a_3 x) \\ \tau_{xy} = -2(b_3 x + c_3 y) \end{array} \right. \rightarrow \text{Linear variation.}$$

If  $a_3 = b_3 = c_3 = 0$   
we get sol. for pure bending

$$N=4: \phi_4 = a_4 x^4 + b_4 x^3 y + c_4 x^2 y^2 + d_4 x y^3 + e_4 y^4$$

$$\nabla^4 \phi = 0 = \cancel{24} a_4 + \cancel{8} c_4 + \cancel{24} e_4 = 0 \rightarrow \text{constraint.}$$

$$\tau_{xx} = 2(c_4 x^2 + 3d_4 x y + 6e_4 y^2); \quad \tau_{yy} = 2(c_4 y^2 + 3b_4 x y + 6a_4 x^2)$$

$$\sigma_{xy} = -3b_5 x^2 - 4c_5 xy - 3d_5 y^2$$

$$N=5: \phi_5 = a_5 x^5 + b_5 x^4 y + c_5 x^3 y^2 + d_5 x^2 y^3 + e_5 x y^4 + f_5 y^5$$

$$\nabla^4 \phi = 0 = \left. \begin{array}{l} x(5a_5 + e_5 + c_5) \cdot 24 \\ y(5f_5 + b_5 + d_5) \cdot 24 \end{array} \right\} \text{constraints}$$

$\Sigma \rightarrow$  cubic.      ( $\psi$ , i.e constant)

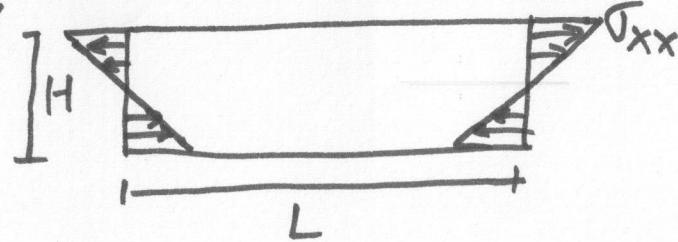
NOTE: For linear in  $(x, y)$  body forces,  $\nabla^4 \phi = 0$

for plane stress & plane strain. So  $\sigma_{xx}, \sigma_{yy}$ , same in both cases. However  $\sigma_{zz} = \nu(\sigma_{xx} + \sigma_{yy})$

$\sigma_{xy}$  same in both cases, and  $\epsilon_{zz} = -\frac{\nu}{1-\nu} (\epsilon_{xx} + \epsilon_{yy})$  in plane stress. Recall also that  $E \rightarrow E/(1-\nu^2), \nu \rightarrow \nu/(1-\nu)$ , in CL for plane stress  $\rightarrow$  plane strain. So strains not same in both cases  $\Rightarrow$  hence displ's not same

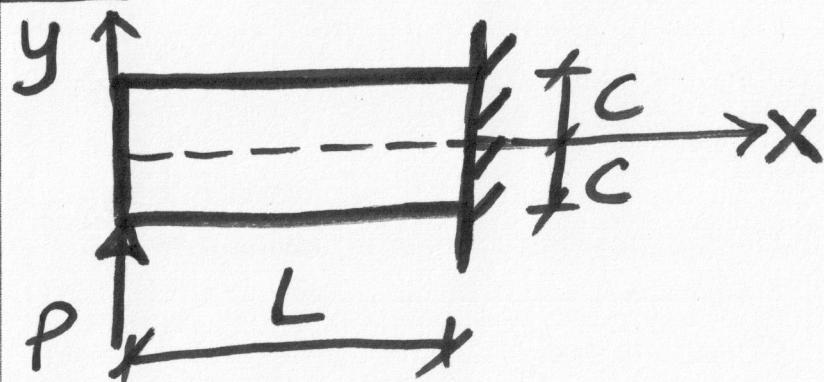


In  $\phi_3$ , if  $a_3 = b_3 = c_3 = 0$ ,  $\sigma_{xx} = 6d_3 y$ ,  $\sigma_{yy} = \sigma_{xy} = 0$   
 ie solution for pure bending  
 w/o restrictions on dimensions  
 $L$ ,  $H$ , or assumption of plane  
 sections remaining plane.



IIT Bombay

### Ex 1 Tip loaded cantilever.



From basic solid mech.  $\rightarrow$   
 $\sigma_{xx} = \frac{My}{I}$ ,  $M \propto x \Rightarrow \sigma_{xx} \propto xy$   
 $\Rightarrow \phi = O(4) = \phi_2 + \phi_3 + \phi_4$

BC's  $\sigma_{xx}|_{x=0} = 0 \Rightarrow c_2 = 0$

(equate coeffs  
 of  $y^0, y^1, y^2$  to zero)  $d_3 = 0$

$$e_4 = 0 = -a_4 - \frac{c_4}{3}$$

$$\sigma_{yy}|_{y=\pm c} = 0 \Rightarrow a_2 \pm b_3 c + c_4 c^2 = 0$$

(coeffs of  $x^0, x^1, x^2$ )  $a_3 \pm b_4 c = 0$   
 $a_4 = 0$

$$\sigma_{xy}|_{y=\pm c} = 0 \Rightarrow -b_2 \mp 2c_3 c - 3d_4 c^2 = 0$$

(coeffs  $x^0, x^1, x^2$ )  $b_3 \pm 2c_4 c = 0$   
 $b_4 = 0$

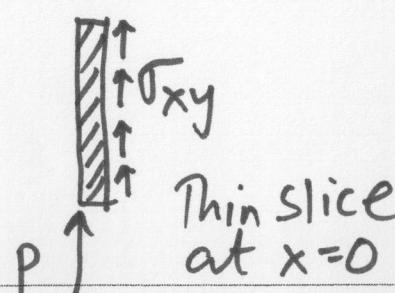
$$\sigma_{xy}|_{x=0} = 0 \Rightarrow b_2 = c_3 = d_4 = 0 \quad \text{relax this.}$$

(coeffs  $y^0, y^1, y^2$ )  $a_2 = \dots = e_4 = 0$ , ie  $\phi = 0$

Sol'n.  $\rightarrow$  all coeffs  $a_2 = \dots = e_4 = 0$  in favor of

so **relax** strong bc  $\sigma_{xy}|_{x=0} = 0$

$$c \int_{-c}^c \sigma_{xy}|_{x=0} dy + P = 0.$$



**NOTE:** This is the weak bc, obvious  $\because \sigma_{xy}|_{x=0}$  must add up to  $P$ .



IIT Bombay

$$\int_{-c}^c \sigma_{xy}|dy = -P \Rightarrow 2(-b_2 c - d_4 c^3) = -P \rightarrow \text{**}$$

$$\text{Solve } \textcircled{*} \textcircled{**} \rightarrow b_2 = \frac{3P}{4c}, d_4 = -\frac{P}{4c^3}$$

other coeffs = 0.

$$\Rightarrow \sigma_{xx} = -\frac{3}{2} \frac{P}{c^3} xy = -\frac{P}{I} xy ; \sigma_{yy} = 0$$

$$\sigma_{xy} = -\frac{3P}{4c} \left(1 - \frac{y^2}{c^2}\right) = -\frac{P}{I} \frac{1}{2} (c^2 - y^2)$$

This soln is exact if P applied not as point load but through a parabolically varying

$$\sigma_{xy}|_{x=0}$$



IIT Bombay

use  $\sigma_{xx} = 0, \sigma_{yy}$   
etc.

## Strains & Displacements:

CL & Str-displ relations  $\rightarrow$

$$\epsilon_{xx} = u_{,x} = \frac{\sigma_{xx}}{E} = -\frac{P}{EI} xy$$

$$\epsilon_{yy} = v_{,y} = -\frac{v}{E} \sigma_{xx} = \frac{vP}{EI} xy$$

$$\epsilon_{xy} = \frac{1}{2}(u_{,x} + v_{,y}) = \frac{1+v}{E} \sigma_{xy} = -\frac{P}{4IG} (k^2 - y^2)$$

Integrate  $\rightarrow$

$$u = -\frac{P}{2EI} x^2 y + f(y)$$

$$v = \frac{vP}{2EI} x y^2 + g(x)$$

$$\text{subst in } \epsilon_{xy} \rightarrow g' - \frac{P}{2EI} x^2 = R_1$$

$$f' + \frac{vP}{2EI} y^2 - \frac{P}{2IG} y^2 = R_2$$

Note: above strains have same functional dependency on  $(x, y)$  as in Tutorial problem

where,

$$\left\{ \begin{array}{l} k_1 + k_2 = \\ -\frac{Pc^2}{2IG} \end{array} \right.$$

(\*)



Integrate for  $f, g, \rightarrow$

$$U = -\frac{P}{2EI} x^2 y - \frac{\nu P}{6EI} y^3 + \frac{P}{6IG} y^3 + R_2 y + R_3$$

$$V = \frac{\nu P}{2EI} x y^2 + \frac{P}{6EI} x^3 + R_1 x + R_4$$

Solve  $R_1, \dots, R_4$  by setting RBM to zero.

R.B. Translation  $\rightarrow$   $U=V=0$  at  $y=0, x=L$   
zero

$$\Rightarrow R_3=0, R_4 = -\frac{PL^3}{6EI} - R_1 L \rightarrow (\star\star\star)$$

R.B Rot. zero:

Horizontal line element at  $x=L, y=0$  has no rot.

(i) Horizontal line element at  $x=L, y=0$  has no rot.

$$\Rightarrow V_{,x}|_{\substack{x=L \\ y=0}} = 0 \rightarrow R_1 = -\frac{PL^2}{2EI} \rightarrow (\star\star\star\star) \rightarrow \text{solve } R_1, \dots, R_4$$

$\hookrightarrow$  same as  $du_{2,j}|_{\substack{x=L \\ y=0}} = u_{2,j} dx_j = 0$

gives  $u_{2,1}=V_{,x}=0$   
at  $x=L, y=0$ .

$$\begin{cases} x=L \\ y=0 \end{cases}$$

for  $dx_j = (1, 0, 0)$



IIT Bombay

(ii) Vertical line element at  $x=L$ ,  $y=0$  has no rot.

$$\Rightarrow u_{,y} \Big|_{\substack{x=L \\ y=0}} = 0 \rightarrow k_2 = \frac{PL^2}{2EI} \rightarrow (\star\star\star\star) \rightarrow \text{solve } k_1, \dots, k_4$$

↳ same as  $du_i \Big|_{\substack{x=L \\ y=0}} = u_{i,j} dx_j = 0$  for  $dx_j = (0, 1, 0)$

↓ gives  $u_{i,2} = u_{,y} = 0$  at  $x=L$ ,  $y=0$ .

(iii) Rotation component  $w_3 = -w_{12} = 0$  at  $x=L$ ,  $y=0$

$$\text{i.e., } (v_{,x} - u_{,y}) \Big|_{\substack{x=L \\ y=0}} = 0 \rightarrow (\star\star\star\star) \rightarrow \text{solve } k_1, \dots, k_4$$

The three conditions [(i), (ii), (iii)] for zero R.B. rotation yield different results for displacements.

For condition (i), elastic curve, i.e.  $v|_{y=0}$ , i.e. disp of neutral line is  $v|_{y=0} = \frac{1}{EI} \left( \frac{P}{6} x^3 - \frac{PL^2}{2} x + \frac{PL^3}{3} \right)$  → same result as Euler-Bernoulli beam theory of basic SM course



IIT Bombay

For conditions (ii) & (iii) you get extra terms, ie,

$$\frac{Pc^2}{2IG} (L-x) \rightarrow \text{for condt (ii)}$$

$$\frac{Pc^2}{4IG} (L-x) \rightarrow \text{for condt (iii).}$$

Now elementary "Bernoulli-Euler" beam theory of CE221 assumes  $\gamma_{xy}=0$ , ie  $G \rightarrow \infty$ . This is also implied for  $\frac{C}{L}$  large, ie slender beam (not thick beam). So put  $G \rightarrow \infty$  or  $C \rightarrow 0$  in condt(ii) or(iii) & you get condt(i) result.



IIT Bombay

NOTE: You must always satisfy strong BC's on long boundaries  $y = \pm C$ . On short boundaries you can try to satisfy strong BC's, else satisfy some/all of these as weak BC's (ie in integral sense).

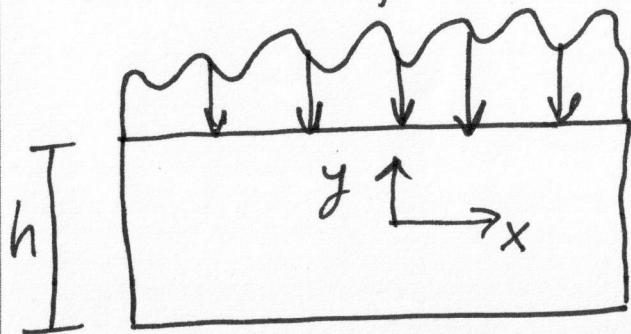


Q: What about satisfying following conditions at fixed end

$$\int_{-C}^C \sigma_{xx} dy = 0 ; \int_{-C}^C \sigma_{xy} dy = -P ; \int_{-C}^C \sigma_{xx} y dy = -PL \quad |_{x=L}$$

A: Since  $\nabla^2 \phi = 0$  <sup>includes</sup> equilibrium eqns, equil is satisfied pointwise. Above conditions are a statement of lumpsum equil (ie of whole beam). Now pointwise equil implies lumpsum equil. So above condts are automatically (identically) satisfied, and they cannot be of any use to obtain any constants.

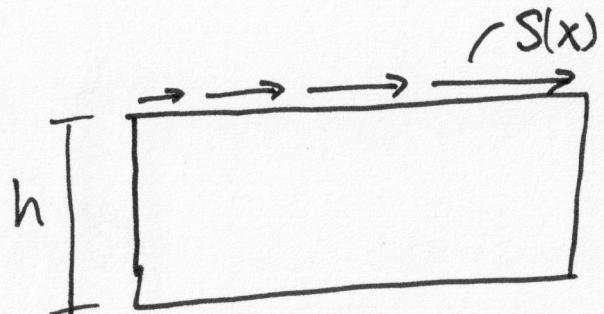
## Order of polynomial.



Normal traction  $W(x) \propto x^n$   
 $\Rightarrow M(x) = \int (W dx)x \propto x^{n+2}$

$$\sigma_{xx} \propto x^{n+2} y$$

$$\therefore \sigma_{xx} = \phi_{,yy} \Rightarrow \phi \text{ contains term } x^{n+2} y^3 \\ \Rightarrow \phi = O(n+5) \text{ polynomial.}$$



Shear traction  $S(x) \propto x^m$

$$\Rightarrow M(x) = \int (S dx) \frac{h}{2} \propto x^{m+1}; \text{ ie } \sigma_{xx} \propto x^{m+1} y$$

$$\text{So } \phi \text{ contains } x^{m+1} y^3; \text{ ie } \phi = O(m+4)$$

$\Rightarrow O(\phi) = \max(n+5, m+4)$  where  $n, m$  are order of normal & shear tractions, respectively.



IIT Bombay

## Symmetry (to reduce O( $\phi$ ))

If beam (including support conditions) symmetric about y-axis, then:

(i) If load symm abt y-axis, i.e.,

$$w(x) = w(-x) ; S(x) = -S(-x)$$

$$\text{then } \sigma_{xx}(x) = \sigma_{xx}(-x) ; \sigma_{xy}(x) = -\sigma_{xy}(-x)$$

i.e.,  $\phi$  = even in x.

(ii) If load antisymm abt y-axis,  $\phi$  = odd in x.

Similarly if beam symm abt x-axis, then:

(iii) Similarly, if load is symm abt x-axis, i.e.,

$$w(y) = w(-y) ; S(y) = -S(-y)$$

$$\text{then } \sigma_{yy}(y) = \sigma_{yy}(-y) ; \sigma_{xy}(y) = -\sigma_{xy}(-y)$$

i.e.  $\phi$  = even in y

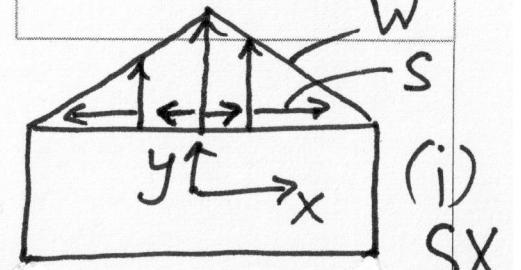
(iv) If load antisymm abt x-axis,  $\phi$  = odd in y

NOTE: Load should "appear" symm or antisymm,

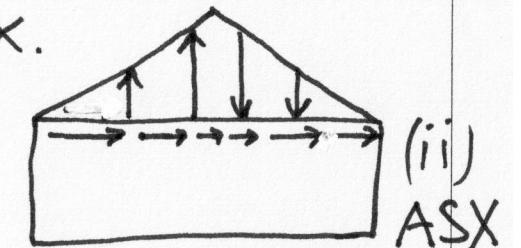
-26- or use sign convention for normal/shear traction



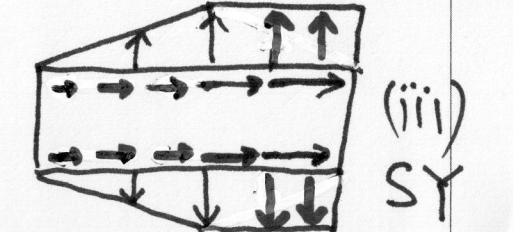
IIT Bombay



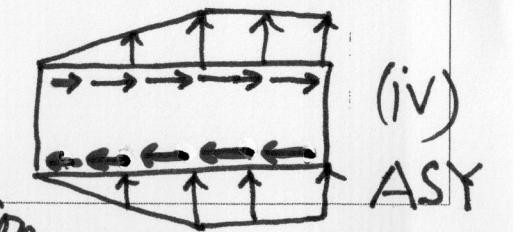
(i)  
SX



(ii)  
ASX



(iii)  
SY



(iv)  
ASY

## Algorithm for Polynomial Solutions

- (i) Obtain  $O(\phi) = \max(n+5, m+4)$ . Then use symmetry/antisymmetry to reduce nos of terms in  $\phi$ .
- (ii) Substitute  $\phi$  in biharmonic eqn to get constraint equations.
- (iii) Substitute  $\phi$  to get  $\sigma_{xx} = \phi_{yy}$ ,  $\sigma_{yy} = \phi_{xx}$ ,  $\tau_{xy} = -\phi_{xy}$
- (iv) Apply BC's  $\rightarrow$  strong for long boundaries ( $y = \text{const}$ ) and if required weak for short boundaries ( $x = \text{const}$ ).

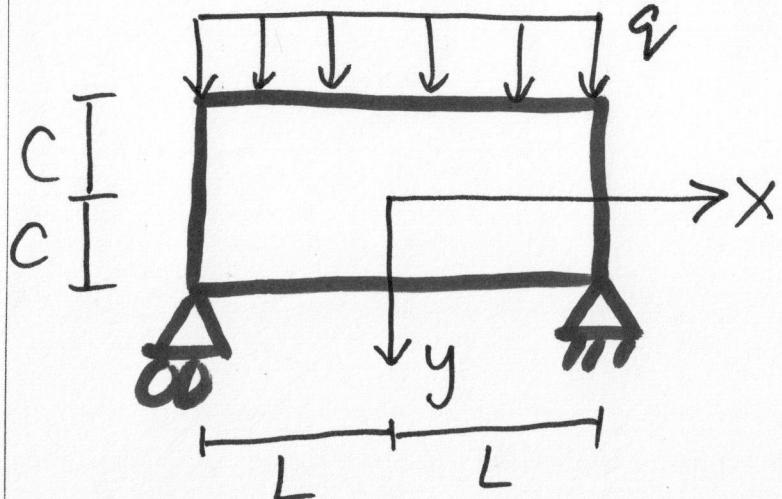
NOTE: The number of equations obtained after applying BC's may exceed nos of ~~constants~~<sup>coefficients</sup> in  $\phi$  that you need to solve for. But solution of these consts will be unique, ie not all the BC equations will be independent.

- (v) Solve constraint eqns & BC eqns for coefficients of  $\phi$ .



IIT Bombay

Ex2 Simply supported uniformly loaded beam.



$$M \propto x^2 \Rightarrow \bar{U}_{xx} \propto x^2 y$$

$$\Rightarrow \phi = O(5)$$

or directly,  $n=0, m=?$

$$O(\phi) = \max(O+5, -) = 5$$



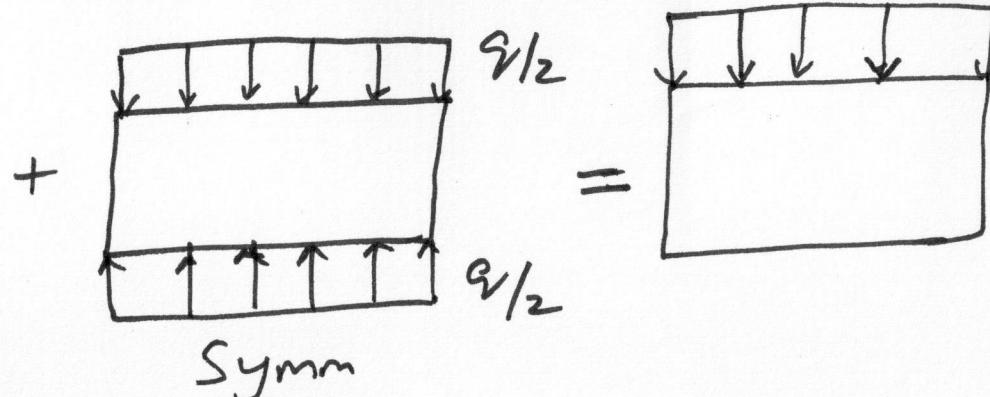
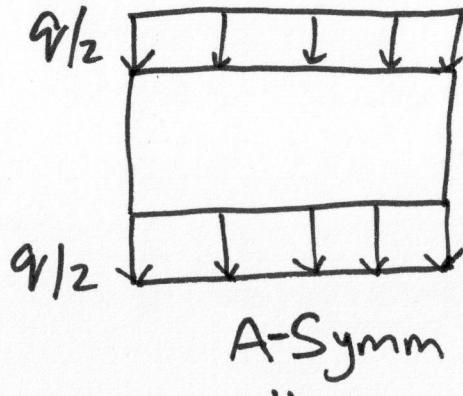
IIT Bombay

$$(i) \phi = \phi_2 + \phi_3 + \phi_4 + \phi_5 \rightarrow 18 \text{ terms} \rightarrow \underbrace{\text{Strong BC's}}_{\left. \begin{array}{l} \bar{U}_{yy} = -q \\ \bar{U}_{yy} \Big|_{y=-c} = 0 \end{array} \right\}} \left. \begin{array}{l} \bar{U}_{xy} \Big|_{y=\pm c} = 0 \\ \int_{-c}^c \bar{U}_{xx} dy = 0 \end{array} \right\}; \underbrace{\text{Weak BC's}}_{\left. \begin{array}{l} \int_{-c}^c (\bar{U}_{xx} dy) x = 0 \\ \int_{-c}^c \bar{U}_{xy} dy \Big|_{x=\pm L} = \mp qL \end{array} \right\}}.$$

Too cumbersome.

(ii) Load symmetric  $\Rightarrow \phi = \text{even in } x \rightarrow 10 \text{ terms} \rightarrow \text{above BC's}$   
 $\text{in } x \rightarrow \text{still too cumbersome.}$

(iii) Split as symmetric & antisymmetric problems.



$$\begin{aligned} &\downarrow \\ S-x, AS-y \\ \phi_{AS} = x^{\text{even}} y^{\text{odd}} \end{aligned}$$

$$\phi_{AS} = 5^{\text{th}} \text{ order}$$

$$\phi = \underbrace{b_3 x^2 y + d_3 y^3 + b_5 x^4 y + d_5 x^2 y^3 + f_5 y^5}_{\phi_{AS}} + \underbrace{\frac{q}{4} x^2}_{\phi_S}$$

$$\text{Constraint eqn} \rightarrow b_5 + d_5 + 5f_5 = 0$$

When applying bc's you can treat A-Symm problem separately (ie only  $\phi_{AS}$ ) or both problems combined (ie  $\phi$ ). We will do former.

$$\sigma_{yy} \Big|_{y=\pm c} = \pm \frac{q}{2} \Rightarrow \pm 2b_3c \pm 2d_5c^3 = \pm \frac{q}{2} \quad (\star) \\ \pm 12b_5c = 0 \\ \sigma_{xy} \Big|_{y=\pm c} = 0 \Rightarrow -2b_3 - 6d_5c^2 = 0 \\ 4b_5 = 0$$



IIT Bombay

$$\int_{-c}^c \sigma_{xx} \Big| dy = 0 \Rightarrow 0 = 0 \text{ (i.s.)}$$

$$\int_{-c}^c \sigma_{xx} \Big| y dy = 0 \Rightarrow 4d_3c^3 + 4d_5L^2c^3 + 8f_5c^5 = 0$$

$$\int_{-c}^c \sigma_{xy} \Big| dy = \mp qL \Rightarrow \pm 4b_3Lc \pm 8b_5L^3c \pm 4d_5Lc^3 = \mp qL \\ -30- \quad \text{Same as } \star \text{ above} \quad \therefore b_5 = 0$$

$$b_3 = \frac{3}{8} \frac{q}{c} ; d_5 = -\frac{q}{8c^3} ; b_5 = 0 ; f_5 = \frac{q}{40c^3}$$

$$d_3 = \frac{q}{8c^3} \left( L^2 - \frac{2}{5} c^2 \right)$$

$$\phi = \frac{q}{40c^3} \left( 15c^2x^2y + 5L^2y^3 - 2c^2y^3 - 5x^2y^3 + y^5 + 10c^3x^2 \right)$$

So only one weak BC gives useful info, other two i.s.

$$\sigma_{xx} = \phi_{yy} = \frac{q}{2I} \left[ (L^2 - x^2)y + \underline{\left( \frac{2}{3}y^2 - \frac{2}{5}c^2y \right)} \right] \quad \left( I = \frac{2}{3}c^3 \right)$$

$$\sigma_{yy} = \phi_{xx} = -\frac{q}{2I} \underline{\left[ \frac{1}{3}y^3 - c^2y + \frac{2}{3}c^3 \right]}$$

$$\sigma_{xy} = -\phi_{xy} = -\frac{q}{2I} \underline{\left[ c^2 - y^2 \right]} x$$

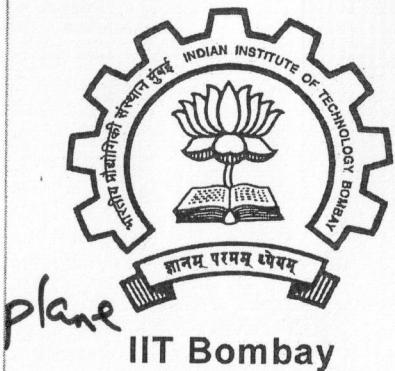
Non-underlined terms  $\rightarrow$  Euler Bernoulli theory  
 Underlined terms  $\rightarrow$  correction to E-B-T, corrections vanish  
 for  $\frac{c}{L} \ll 1$  (ie  $c \rightarrow 0, y \rightarrow 0$ )



IIT Bombay

Deflections obtained in usual manner by integrating SD relations (HW4, P1).

BC's:  $v \Big|_{\substack{y=-c \\ x=\pm L}} = 0$  prevents RB translation - y  
 & RB rotation - xy plane



$u \Big|_{\substack{y=-c \\ x=-L}} = 0$  prevents RB transl - x.

$$\text{Result} \rightarrow v \Big|_{y=0} = \frac{5}{24} \frac{qL^4}{EI} \left[ \underbrace{\left[ 1 - \frac{6}{5} \left( \frac{x}{L} \right)^2 + \frac{1}{5} \left( \frac{x}{L} \right)^4 + \underbrace{\frac{12}{5} \left( \frac{c}{L} \right)^2 \left\{ \left( \frac{4}{5} + \frac{\nu}{2} \right) \left( 1 - \left( \frac{x}{L} \right)^2 \right) \right.}_{\text{Term I}} \right.}_{\left. + \left( \frac{1}{64} - \frac{\nu}{480} \right) \left( \frac{h}{L} \right)^2 \right] \left. \right]$$

Term I  $\rightarrow$  Classical E-BT

Term II  $\rightarrow$  Correction due to shear effect in deformation, Term IIa  
 useful when  $\frac{c}{L} \ll 1$

Alternatively, if supports at  $y=0$ , then apply above BC's at  $y=0$  instead of  $y=-c$ . Term IIa vanishes (Timoshenko, Shames & Dym).

Alternatively,  $u, v, (u_y - v_x)$  all zero at  $x=-L, y=-c$ . Gives diff result.

## SEMI - INVERSE METHOD.

STEP-I Based on loading & BC's, assume functional form for some/all of stresses/displ's.

STEP-II Satisfy governing equations to obtain explicit form of solution; then satisfy BC's to get constants.

For stress function approach, assume fun form of stresses, integrate to obtain fun form of  $\phi$ , then make  $\phi$  satisfy biharmonic eqn to get explicit  $\phi$ , then satisfy BC's to get solution.

STEP-I  $\therefore \sigma_{yy}|_y = \underbrace{\pm c}_{\rightarrow 0} - q$ , ie indep of  $x$ , assume  $\sigma_{yy} = f(y)$

$$\Rightarrow \phi_{xx} = f(y) \rightarrow \phi = \frac{x^2}{2}f(y) + xg(y) + h(y)$$



IIT Bombay

## STEP-II

$$\nabla^4 \phi = \frac{x^2}{2} f^{IV} + x g^{IV} + h^{IV} + 2f'' = 0$$

$$\Rightarrow f^{IV} = g^{IV} = h^{IV} + 2f'' = 0$$

$$f = Ay^3 + By^2 + Cy + D$$

$$g = Ey^3 + Fy^2 + Gy \quad (\text{const in } g \text{ dropped as it won't affect stresses})$$

$$h^{IV} = -2f'' = -12Ay - 4B \Rightarrow h = \frac{A}{10}y^5 - \frac{B}{6}y^4 + Hy^3 + Ky^2$$

$$\Rightarrow \phi = \frac{x^2}{2} (Ay^3 + By^2 + Cy + D) + x(Ey^3 + Fy^2 + Gy)$$

$$- \frac{A}{10}y^5 - \frac{B}{6}y^4 + Hy^3 + Ky^2$$

Stresses :  $\sigma_{xx} = \phi_{,yy} = \frac{x^2}{2}(6Ay + 2B) + x(6Ey + 2F) - 2Ay^3 - 2By^2$   
 $+ 6Hy + 2K.$

$$\sigma_{yy} = \phi_{,xx} = Ay^3 + By^2 + Cy + D$$

$$\sigma_{xy} = -\phi_{xy} = -x(3Ay^2 + 2By + C) - (3Ey^2 + 2Fy + G)$$



IIT Bombay

Apply BC's (strong & weak). Some weak BC's will be redundant (i.e, I.S.), ie

$$\int_{-C}^C \sigma_{xy} dy = \mp qL \text{ in this case. Also you can}$$

use symmetry in 'x' to reduce work  $\rightarrow$  get  $(F, F, G) = 0$



IIT Bombay

## FOURIER SERIES METHOD.

Polynomial Solutions possible, when loading only (tractions) can be written as power series.  
When not so, e.g. concentrated / discontinuous load, we use Fourier Series.



IIT Bombay

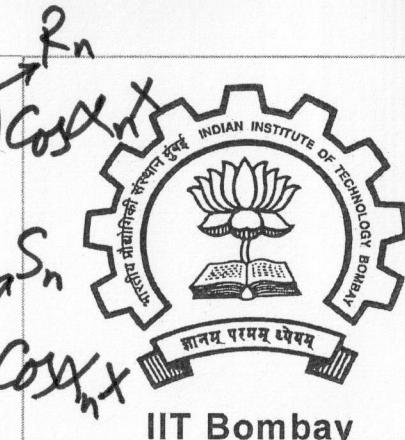
Consider,

$$\phi = \sin(\alpha x) f(y) \text{ or } \phi = \cos(\alpha x) f(y) \quad (\text{when loading a top/bot faces}).$$

$$\nabla^4 \phi = 0 \Rightarrow (f^{IV} - 2\alpha^2 f'' + \alpha^4 f) = 0 \quad (\because \sin(\alpha x), \cos(\alpha x) \text{ are non-zero}).$$

$$f = A \cosh \alpha y + B \sinh \alpha y + C y \cosh \alpha y + D y \sinh \alpha y$$

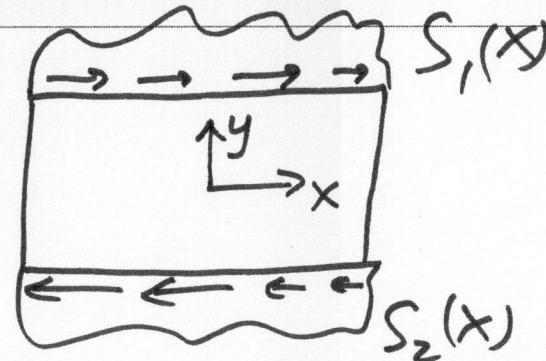
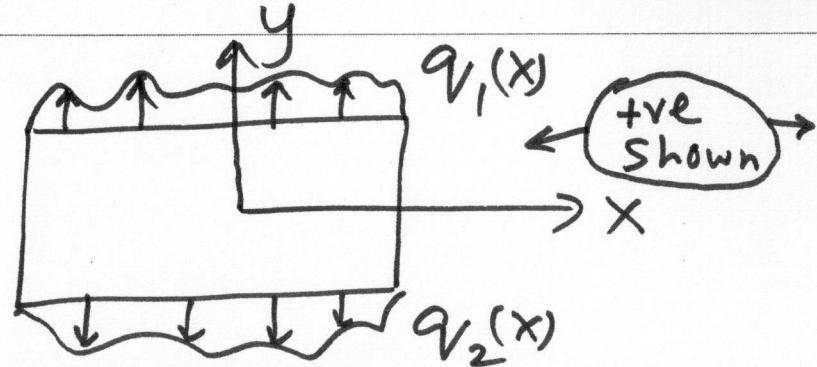
$$\begin{aligned} \phi &= \sum_{n=1}^{\infty} (A_n \cosh \alpha_n y + D_n y \sinh \alpha_n y) \overset{P_n}{\cos \alpha_n x} \rightarrow \frac{f_1, g_1 \text{ problem} \rightarrow S_x S_y,}{A x A y} \\ &\quad + \sum_{n=1}^{\infty} (A'_n \cosh \alpha_n y + D'_n y \sinh \alpha_n y) \overset{P_n}{\sin \alpha_n x} \rightarrow \frac{f_2, g_2 \rightarrow A x S_y,}{S_x A y} \\ &\quad + \sum_{n=1}^{\infty} (B_n \sinh \alpha_n y + C_n y \cosh \alpha_n y) \overset{Q_n}{\cos \alpha_n x} \rightarrow \frac{f_3, g_3 \rightarrow S_x A_y,}{A x S_y} \\ &\quad + \sum_{n=1}^{\infty} (B'_n \sinh \alpha_n y + C'_n y \cosh \alpha_n y) \overset{Q_n}{\sin \alpha_n x} \rightarrow \frac{f_4, g_4 \rightarrow A x A_y,}{S_x S_y} \end{aligned}$$



$$\begin{aligned} \sigma_{xx} &= \sum (A_n \alpha_n^2 \cosh \alpha_n y + 2D_n \alpha_n \sinh \alpha_n y + D_n \alpha_n^2 y \sinh \alpha_n y) \cos \alpha_n x \\ A_x S_y &\leftarrow + \sum ( ) \rightarrow R_n \sin \alpha_n x \\ S_x A_y &\leftarrow + \sum (B_n \alpha_n^2 \sinh \alpha_n y + 2C_n \alpha_n \sinh \alpha_n y + C_n \alpha_n^2 y \cosh \alpha_n y) \cos \alpha_n x \\ A_x A_y &\leftarrow + \sum ( ) \rightarrow S_n \sin \alpha_n x \end{aligned}$$

$$\begin{aligned} \sigma_{yy} &= - \sum P_n \alpha_n^2 \cos \alpha_n x \\ - \sum P_n \alpha_n^2 \sin \alpha_n x &\leftarrow S_x S_y \\ - \sum Q_n \alpha_n^2 \cos \alpha_n x &\leftarrow A_x S_y \\ - \sum Q_n \alpha_n^2 \sin \alpha_n x &\leftarrow S_x A_y \\ &\leftarrow A_x A_y \end{aligned}$$

$$\begin{aligned} \tau_{xy} &= + \sum (A_n \alpha_n^2 \sinh \alpha_n y + D_n \alpha_n \sinh \alpha_n y + D_n \alpha_n^2 y \cosh \alpha_n y) \sin \alpha_n x \\ - \sum ( ) \cos \alpha_n x &\rightarrow T_n \rightarrow A_x A_y \\ + \sum (B_n \alpha_n^2 \cosh \alpha_n y + C_n \alpha_n \cosh \alpha_n y + C_n \alpha_n^2 y \sinh \alpha_n y) \sin \alpha_n x &\rightarrow U_n \rightarrow S_x A_y \\ - \sum ( ) \cos \alpha_n x &\rightarrow U_n \rightarrow A_x S_y \\ &\rightarrow S_x S_y \end{aligned}$$



IIT Bombay

$$\text{Define, } \begin{cases} f_1(x) = +q_1(x) + q_1(-x) + q_2(x) + q_2(-x) \rightarrow S_x, S_y \\ f_2(x) = + - + - \rightarrow A_x, S_y \end{cases}$$

$$f_3(x) = + + - - \rightarrow S_x, A_y$$

$$f_4(x) = + - - + \rightarrow A_x, A_y$$

$$\begin{cases} g_1(x) = +S_1(x) - S_1(-x) - S_2(x) + S_2(-x) \rightarrow A_x, A_y \\ g_2(x) = + + - - \rightarrow S_x, A_y \end{cases}$$

$$g_3(x) = + - + - \rightarrow A_x, S_y$$

$$g_4(x) = + + + + \rightarrow S_x, S_y$$

So we decompose into the above 4 sub-problems, i.e.,  $(f_1, g_1), (f_2, g_2), (f_3, g_3), (f_4, g_4)$

$$\Rightarrow q_1 = (f_1 + f_2 + f_3 + f_4)/4$$

$$q_2 = (f_1 + f_2 - f_3 - f_4)/4$$

$$S_1 = (g_1 + g_2 + g_3 + g_4)/4$$

$$S_2 = (-g_1 - g_2 + g_3 + g_4)/4$$

$\rightarrow$  So, eg,  $f_3$  is Ay

$\rightarrow$  So, eg,  $g_2$  is Ay



IIT Bombay

Here it's possible to satisfy one of the short-edge BC's in strong form. Say,

$$\sigma_{xx} = 0 \text{ at } x = \pm L \Rightarrow \alpha_n = (2n-1) \frac{\pi}{2L} \text{ for } f_1, f_3 \quad \left\{ n=1, 2, \dots \right.$$

$$= \frac{n\pi}{L} \text{ for } f_2, f_4 \quad \left. \right\}$$

Strong BC's:

$$\begin{aligned} \sigma_{yy} \Big|_{y=c} &= q_1 = \frac{1}{4} f_1 \\ &= \frac{1}{4} f_2 \\ &= \frac{1}{4} f_3 \\ &= \frac{1}{4} f_4 \end{aligned}$$

$$\begin{aligned} \text{Note: } \sigma_{yy} \Big|_{y=-c} &= q_2 = \frac{1}{4} f_1 \\ &= \frac{1}{4} f_2 \\ &= -\frac{1}{4} f_3 \\ &= -\frac{1}{4} f_4 \end{aligned}$$

gives no new info.

$\because f_1, f_2$  are Sy  
&  $f_3, f_4$  are Ay

$$\Rightarrow \frac{1}{4}f_1 = -\sum P_n \Big|_C \alpha_n^2 \cos \alpha_n x \rightarrow f_1 \text{ problem}$$

$$\frac{1}{4}f_2 = -\sum P_n \Big|_C \alpha_n^2 \sin \alpha_n x \rightarrow f_2$$

$$\frac{1}{4}f_3 = -\sum Q_n \Big|_C \alpha_n^2 \cos \alpha_n x \rightarrow f_3$$

$$\frac{1}{4}f_4 = -\sum Q_n \Big|_C \alpha_n^2 \sin \alpha_n x \rightarrow f_4$$

$$\Rightarrow \text{for } f_1 \rightarrow \underset{\text{prblm}}{\frac{1}{4} \int_{-L}^L} f_1 \cos \alpha_n x dx = -P_n \Big|_C \alpha_n^2 L = -\alpha_n^2 L (A_n \cosh \alpha_n C + D_n C \sinh \alpha_n C)$$

$$f_2 \rightarrow \frac{1}{4} \int_{-L}^L f_2 \sin \alpha_n x dx = -P_n \Big|_C \alpha_n^2 L = -\alpha_n^2 L ( )$$

$$f_3 \rightarrow \frac{1}{4} \int_{-L}^L f_3 \cos \alpha_n x dx = -Q_n \Big|_C \alpha_n^2 L = -\alpha_n^2 L (B_n \sinh \alpha_n C + C_n C \cosh \alpha_n C)$$

$$f_4 \rightarrow \frac{1}{4} \int_{-L}^L f_4 \sin \alpha_n x dx = -Q_n \Big|_C \alpha_n^2 L = -\alpha_n^2 L ( )$$

(A)

$$\text{Shear BC} \rightarrow \sigma_{xy} \Big|_{y=C} = S_1 = \frac{1}{4}g_1 \\ = \frac{1}{4}g_2 \\ = \frac{1}{4}g_3 \\ = \frac{1}{4}g_4$$

Note:  $\sigma_{xy} \Big|_{y=-C} = S_2 = -\frac{1}{4}g_1$   
 $= -\frac{1}{4}g_2$   
 $= \frac{1}{4}g_3$   
 $= \frac{1}{4}g_4$

gives no new info  
 $\therefore g_1, g_2$  are  $A_y$   
 $\& g_3, g_4$  are  $S_y$



$$\Rightarrow \frac{1}{4}g_1 = \sum T_n |_C \sin \alpha_n x$$

$$\frac{1}{4}g_2 = -\sum T_n |_C \cos \alpha_n x$$

$$\frac{1}{4}g_3 = \sum U_n |_C \sin \alpha_n x$$

$$\frac{1}{4}g_4 = -\sum U_n |_C \cos \alpha_n x$$

$$\Rightarrow \text{for } g_1 \rightarrow \underset{\text{prblm}}{\frac{1}{4} \int_{-L}^L g_1 \sin \alpha_n x dx} = T_n |_C L = L \left[ A_n \alpha_n^2 \sinh \alpha_n c + D_n \alpha_n \sinh \alpha_n c + D_n \alpha_n^2 c \cosh \alpha_n c \right]$$

$$\textcircled{B} \leftarrow g_2 \rightarrow -\frac{1}{4} \int_{-L}^L g_2 \cos \alpha_n x dx = T_n |_C L = L [ \downarrow ]$$

$$g_3 \rightarrow \frac{1}{4} \int_{-L}^L g_3 \sin \alpha_n x dx = U_n |_C L = L \left[ B_n \alpha_n^2 \cosh \alpha_n c + C_n \alpha_n \cosh \alpha_n c + C_n \alpha_n^2 c \sinh \alpha_n c \right]$$

$$g_4 \rightarrow -\frac{1}{4} \int_{-L}^L g_4 \cos \alpha_n x dx = U_n |_C L = L [ \downarrow ]$$

Solve  $\textcircled{A}_1, \textcircled{B}_1, \textcircled{A}_2, \textcircled{B}_2, \textcircled{A}_3, \textcircled{B}_3, \textcircled{A}_4, \textcircled{B}_4$  for  $(A_n, D_n)$   
and  $(B_n, C_n)$



We get,

$$D_n = \frac{\sinh \alpha_n C \int_{-L}^L \left\{ f_1 \cos \alpha_n x dx \right\} + \cosh \alpha_n C \int_{-L}^L \left\{ g_1 \sin \alpha_n x dx \right\}}{\int_{-L}^L \left\{ f_2 \sin \alpha_n x dx \right\}}$$

$$\frac{L (\alpha_n^2 C + \alpha_n \sinh \alpha_n C \cosh \alpha_n C)}{}$$

$$A_n = \frac{-\frac{1}{4} \int_{-L}^L \left\{ f_1 \cos \alpha_n x dx \right\} - \alpha_n^2 L D_n C \sinh \alpha_n C}{\int_{-L}^L \left\{ f_2 \sin \alpha_n x dx \right\}}$$

$\rightarrow (f_1, g_1),$   
 $(f_2, g_2)$

$$C_n = \frac{\cosh \alpha_n C \int_{-L}^L \left\{ f_3 \cos \alpha_n x dx \right\} \pm \sinh \alpha_n C \int_{-L}^L \left\{ g_3 \sin \alpha_n x dx \right\}}{\int_{-L}^L \left\{ f_4 \sin \alpha_n x dx \right\}}$$

$$\frac{\alpha_n^2 L \cosh \alpha_n C}{L (-\alpha_n^2 C + \alpha_n \sinh \alpha_n C \cosh \alpha_n C)}$$

$$B_n = \frac{-\frac{1}{4} \int_{-L}^L \left\{ f_3 \cos \alpha_n x dx \right\} - \alpha_n^2 L C_n C \cosh \alpha_n C}{\int_{-L}^L \left\{ f_4 \sin \alpha_n x dx \right\}}$$

$\rightarrow (f_3, g_3),$   
 $(f_4, g_4)$



IIT Bombay

Procedure :

(i) From give loads  $q_1, q_2, s_1, s_2$ , obtain  $f_1, \dots, f_4, g_1, \dots, g_4$ , as given on p 38.

(ii) Obtain  $A_n, \dots, D_n$  (p. 42)

(iii) Obtain stresses (p. 37).



IIT Bombay

All above expressions are easily programmable.

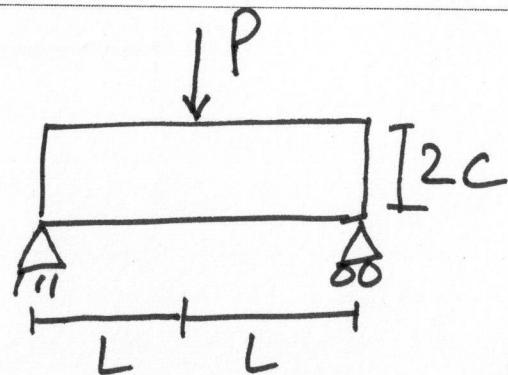
# If loads are periodic in  $x$ , you will need finite no. of terms in the series soln (ie  $n = \text{finite}$ ).

# If loads are not periodic, truncate to  $n$ -term series solution, where  $n$  is obtained by convergence, ie  
 $|(\text{soln})_{n+1} - (\text{soln})_n| / |(\text{soln})_n| < \epsilon$ . ( $\epsilon$  small number)

NOTE: Strong BC on short edge satisfied for  $\tau_{xx}$

Weak BC on short edge for  $\tau_{xy}$  will be automatically satisfied — dont need to check it.

(Ex)



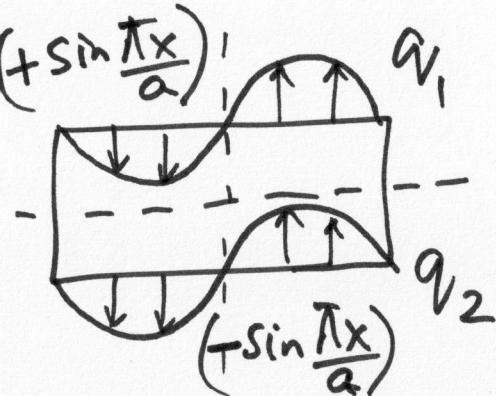
$$q_1(x) = P \delta(x-0); q_2 = s_1 = s_2 = 0$$

$$f_1 = f_3 = 2P \delta(x-0)$$

$$f_2 = f_4 = g_1 = g_2 = g_3 = g_4 = 0.$$

Proceed to find  $A_n, \dots, D_n$  & soln  
for stresses.

Ex



$(q_1, q_2)$  are  $A_x A_y \rightarrow$  so its  $f_4$  problem.

$f_1 = f_2 = f_3 = 0, f_4 = 4 \sin \frac{\pi x}{a} \rightarrow$  proceed for soln.



IIT Bombay

## 2D PROBLEMS IN POLAR COORDINATES

Transformation of equilibrium equations:

$$\frac{\sigma_{rr} + \sigma_r - \sigma_\theta}{r} + \frac{\sigma_{r\theta, \theta}}{r} + B_r = 0 \rightarrow r\text{-eqn}$$

$$\frac{\sigma_{r\theta, r}}{r} + \frac{2\sigma_{r\theta}}{r} + \frac{\sigma_{\theta, \theta}}{r} + B_\theta = 0 \rightarrow \theta\text{-eqn.}$$



IIT Bombay

Transformation of derivatives & Compatibility (biharmonic)  
equation:

$$\frac{\partial}{\partial x} = \frac{\partial}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial}{\partial \theta} \frac{\partial \theta}{\partial x} ; \quad x = r \cos \theta, \quad y = r \sin \theta$$

$$\frac{\partial r}{\partial x} = \frac{x}{r} = \cos \theta; \quad \frac{\partial r}{\partial y} = \frac{y}{r} = \sin \theta; \quad \frac{\partial \theta}{\partial x} = -\frac{\sin \theta}{r}; \quad \frac{\partial \theta}{\partial y} = \frac{\cos \theta}{r}$$

$$\frac{\partial}{\partial x} = \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta}$$

$$\frac{\partial^2}{\partial x^2} = \left( \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) \left( \cos \theta \frac{\partial}{\partial r} - \frac{\sin \theta}{r} \frac{\partial}{\partial \theta} \right) = \cos^2 \theta \frac{\partial^2}{\partial r^2} + \sin^2 \theta \left( \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) - \sin \theta \cos \theta \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial \theta} \right)$$

$$= -\frac{\sin \theta \cos \theta}{r} \frac{\partial}{\partial r} \left( \frac{\partial}{\partial \theta} \right) + \frac{\sin \theta \cos \theta}{r^2} \frac{\partial^2}{\partial \theta^2} = -\sin \theta \cos \theta \frac{\partial^2}{\partial r \partial \theta}$$

$$\Rightarrow \frac{\partial^2}{\partial x^2} = C^2 \theta \frac{\partial^2}{\partial r^2} + S^2 \theta \left( \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) - 2 S \theta C \theta \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial \theta} \right)$$

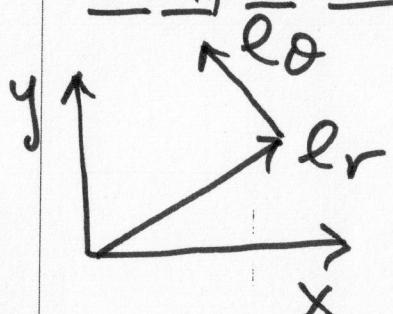
For  $\frac{\partial}{\partial y}$ ,  $\frac{\partial^2}{\partial y^2}$  do  $\{S\theta \rightarrow -C\theta\}$  in  $\frac{\partial}{\partial x}$ ,  $\frac{\partial^2}{\partial x^2}$   
 $\{C\theta \rightarrow S\theta\}$

$$\frac{\partial^2}{\partial x \partial y} = -S \theta C \theta \left( \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} - \frac{\partial^2}{\partial r^2} \right) + (C^2 \theta - S^2 \theta) \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial}{\partial \theta} \right)$$

Thus,  $\nabla_{xy}^2 = \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} = \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$

$$\nabla_{xy}^4 = \nabla_{xy}^2 \nabla_{xy}^2 \Rightarrow \boxed{\left( \frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right)^2 \phi = 0} \rightarrow \text{COMPATIBILITY EQN.}$$

Transformation of stresses & stress function relations.



$$\tau_r = \sigma_{xx} C^2 \theta + \sigma_{yy} S^2 \theta + 2 \sigma_{xy} S \theta C \theta$$

$$\tau_\theta = \sigma_{xx} S^2 \theta + \sigma_{yy} C^2 \theta - 2 \sigma_{xy} S \theta C \theta$$

$$\tau_{r\theta} = -(\sigma_{xx} - \sigma_{yy}) S \theta C \theta + \sigma_{xy} (C^2 \theta - S^2 \theta)$$



IIT Bombay

Substitute  $\sigma_{xx} = \phi_{,yy}$ ,  $\sigma_{yy} = \phi_{,xx}$ ,  $\sigma_{xy} = -\phi_{,xy}$   
in transformation relation of stresses (\*), and  
transform  $x, y$  derivatives on  $\phi$  to  $r, \theta$  derivatives  
(bot. p. 45, top p. 46), get,



IIT Bombay

$$\sigma_r = \frac{1}{r} \phi_{,r} + \frac{1}{r^2} \phi_{,\theta\theta}$$

$$\sigma_\theta = \phi_{,rr}$$

$$\sigma_{r\theta} = -\frac{\partial}{\partial r} \left( \frac{1}{r} \phi_{,\theta} \right)$$

Transformation of strain displ relations.

Displacements  $(u, v) \rightarrow$  Cartesian,  $(u_r, u_\theta) \rightarrow$  polar.

$$u = c\theta u_r - s\theta u_\theta ; \quad v = s\theta u_r + c\theta u_\theta$$

$$e_{xx} = u_{,x} = c^2 \theta e_r + s^2 \theta e_\theta - 2 e_r s \theta c \theta = c^2 \theta u_{r,r} - c \theta s \theta u_{\theta,r}$$

use transf of strains

$$- \frac{s\theta}{r} (-s\theta u_r - c\theta u_\theta + c\theta u_{r,\theta} - s\theta u_{\theta,\theta})$$

use transf of displs & derivatives.

Similarly for  $\epsilon_{yy}$ ,  $\epsilon_{xy}$ . Then solve 3 eqns  
for  $\epsilon_r$ ,  $\epsilon_\theta$ ,  $\epsilon_{r\theta}$  in terms of  $u_r$ ,  $u_\theta$  and their  
derivatives.

Result,



IIT Bombay

$$\epsilon_r = u_{r,r}$$

$$\epsilon_\theta = \frac{u_r}{r} + \frac{1}{r} u_{\theta,\theta}$$

$$\epsilon_{r\theta} = \frac{1}{r} (u_{\theta,r} + \frac{1}{r} u_{r,\theta} - \frac{u_\theta}{r})$$

### Transformation of Constitutive Relations.

These remain same, except  $\epsilon_{xx} \rightarrow \epsilon_r$ ,  $\sigma_{xx} \rightarrow \tau_r$ ,  $\epsilon_{yy} \rightarrow \epsilon_\theta$   
 $\sigma_{yy} \rightarrow \tau_\theta$ ,  $\epsilon_{xy} \rightarrow \epsilon_{r\theta}$ ,  $\sigma_{xy} \rightarrow \tau_{r\theta}$

$$\epsilon_r = \frac{1}{E} (\tau_r - \nu \tau_\theta)$$

$$\epsilon_\theta = \frac{1}{E} (\tau_\theta - \nu \tau_r)$$

$$\epsilon_{r\theta} = \frac{1+\nu}{E} \tau_{r\theta}$$

$$\epsilon_z = -\frac{\nu}{E} (\tau_r + \tau_\theta)$$

→ PLANE  
STRESS

$$\epsilon_r = \frac{1-\nu^2}{E} \left[ \tau_r - \frac{\nu}{1-\nu} \tau_\theta \right]$$

$$\epsilon_\theta = \frac{1-\nu^2}{E} \left[ \tau_\theta - \frac{\nu}{1-\nu} \tau_r \right] \rightarrow \text{PLANE STRAIN.}$$

$$\epsilon_{r\theta} = \frac{1+\nu}{E} \tau_{r\theta}$$

i.e.  
 $E \rightarrow E / (1+\nu)^2$   
 $\nu \rightarrow \nu / (1-\nu)$

in plane stress. ←

## AXISYMMETRIC PROBLEMS.

Loading, & hence stresses/strains, are invariant about an axis (i.e., independent of  $\theta$ ). Hence  $\phi = \phi(r)$  (except the case  $\phi = C\theta$ , which we will treat separately). Note that this  $\Rightarrow$  that displacements are indep of  $\theta$ .



IIT Bombay

$$\nabla^4 \phi = \left( \frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} \right)^2 = \phi^{IV} + \frac{2}{r} \phi^{III} - \frac{1}{r^2} \phi^{II} + \frac{1}{r^3} \phi' = 0$$

put  $r = e^t$  to convert to ODE with constant coeffs.

$$\left\{ \begin{array}{l} \frac{d\phi}{dr} = \frac{d\phi}{dt} \frac{dt}{dr} = e^{-t} \frac{d\phi}{dt}; \quad \frac{d^2\phi}{dr^2} = e^{-2t} \left[ -\frac{d\phi}{dt} + \frac{d^2\phi}{dt^2} \right] \\ \frac{d^3\phi}{dr^3} = e^{-3t} \left[ 2\frac{d\phi}{dt} - 3\frac{d^2\phi}{dt^2} + \frac{d^3\phi}{dt^3} \right]; \quad \frac{d^4\phi}{dr^4} = e^{-4t} \left[ -6\frac{d\phi}{dt} + 11\frac{d^2\phi}{dt^2} \right. \end{array} \right.$$

$$\left. \left. -6\frac{d^3\phi}{dt^3} + \frac{d^4\phi}{dt^4} \right] \right\}$$

$$\Rightarrow \nabla^4 \phi = \frac{d^4 \phi}{dt^4} - 4 \frac{d^3 \phi}{dt^3} + 4 \frac{d^2 \phi}{dt^2} = 0$$

$$\phi = e^{\lambda t} \rightarrow \lambda^4 - 4\lambda^3 + 4\lambda^2 = 0 \rightarrow \lambda = 0, 0, 2, 2$$

$$\phi = A^* + B^*t + C^*e^{2t} + D^*te^{2t}$$

$$\phi = A \ln r + B r^2 \ln r + C r^2 + D$$

$$\Rightarrow \boxed{\begin{aligned}\sigma_r &= \frac{1}{r} \phi_{,r} = \frac{A}{r^2} + B(1+2\ln r) + 2C \\ \sigma_\theta &= \phi_{,rr} = -\frac{A}{r^2} + B(3+2\ln r) + 2C \\ \tau_{r\theta} &= -\left(\frac{1}{r}\phi_{,\theta}\right)_r = 0\end{aligned}}$$

# If  $r=0$  is part of domain  $\Rightarrow A=B=0, \sigma_r=\sigma_\theta=2C$  for finite stresses.

Displacements :

$$\epsilon_r = u_{r,r} = \frac{1}{E} (\sigma_r - \nu \sigma_\theta)$$

$$\Rightarrow u_r = \frac{1}{E} \left[ -\frac{A}{r} (1+\nu) + 2B(1-\nu)r \ln r - B(1+\nu)r + 2C(1-\nu)r \right] + f(\theta)$$



IIT Bombay

$$u_{\theta,\theta} = r e_\theta - u_r = r \frac{1}{E} (\tau_\theta - \nu \tau_r) - u_r$$

$$= \frac{1}{E} 4Br - f(\theta)$$

$$\Rightarrow u_\theta = \frac{4Br\theta}{E} - \int f(\theta) d\theta + g(r)$$

Const of integr  
absorbed in  
 $g(r)$

$$e_{r\theta} = 0 \Rightarrow u_{\theta,r} + \frac{1}{r} u_{r,\theta} - \frac{u_\theta}{r} = \cancel{\frac{4B\theta}{E}} + g' + \frac{1}{r} f' - \cancel{\frac{4B\theta}{E}} + \frac{1}{r} \int f d\theta - \cancel{\frac{g}{r}} = 0$$

$$\Rightarrow g - r g' = Z = f' + \int f d\theta$$

(Const)

$$f'' + f = 0 \rightarrow f = H \sin \theta + K \cos \theta \rightarrow Z = H c \theta - K s \theta - H c \theta + K s \theta = 0$$

$$rg' = g \rightarrow g = Gr$$

$$\Rightarrow u_r = \frac{1}{E} \left[ -(1+\nu) \frac{A}{r} + 2(1-\nu) Br \ln r - B(1+\nu)r + 2C(1-\nu)r \right]$$

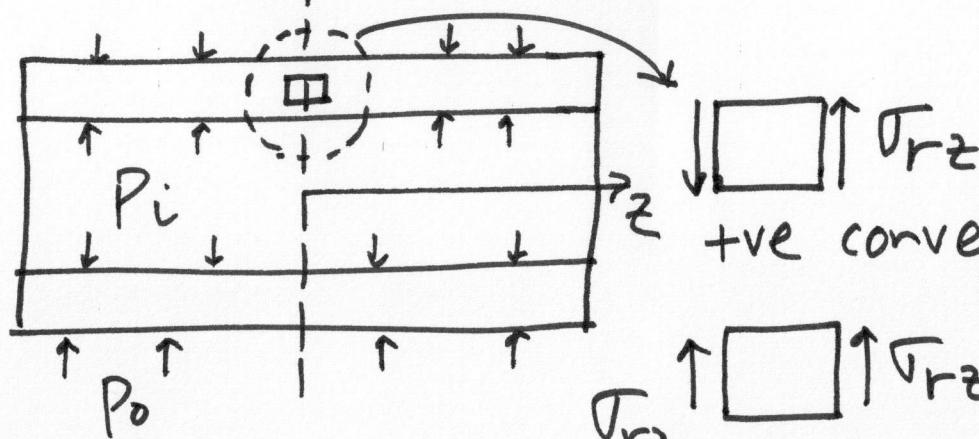
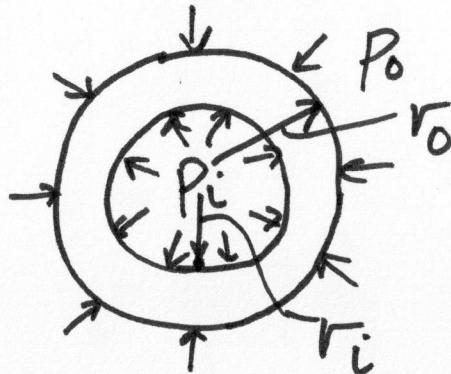
$\therefore + H \sin \theta + K \cos \theta -$

$$u_\theta = \frac{4}{E} Br\theta + H \cos \theta - K \sin \theta + Gr$$



IIT Bombay

# (I) Thick Walled Cylinder subject to pressure



Symmetry in  $z$ -direction

$$\Rightarrow \tau_{rz} = \tau_{oz} = 0$$

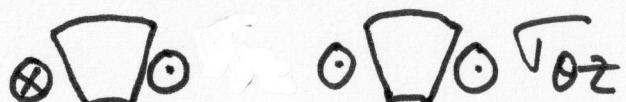
due to symmetry in  $z$ -dir.

$\otimes \square \odot \tau_{oz}$   
tve convention



due to symmetry in  $z$ -dir

Also



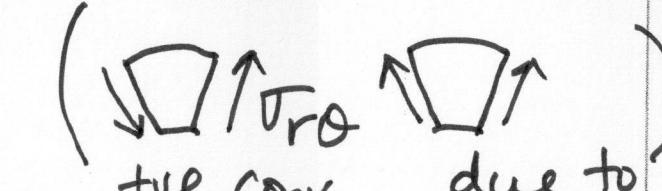
+ve conv. due to axisymm  
(ie symm in  $\theta$ -dir)

$$\Rightarrow \tau_{oz} = 0.$$

Case A: Ends un-capped (i.e open)  $\Rightarrow \tau_{zz} = 0$   
and unrestrained

Thus its plane stress problem ( $\sigma_{zz} = \sigma_{rz} = \sigma_{\theta z} = 0$ )

Axisymmetry  $\Rightarrow \sigma_{r\theta} = 0$



Axisymm  $\Rightarrow u_\theta = 0 \Rightarrow B = 0$  (also due to single-valuedness)

$$\Rightarrow G_r = \underbrace{K \sin \theta - H \cos \theta}_{G=0} = \text{const} = 0$$

$$u_r \neq u_r(\theta) \Rightarrow H \sin \theta + K \cos \theta = 0 \rightarrow K = H = 0$$

Stress BC's:  $\sigma_r|_{r=r_0} = -p_0$  ;  $\sigma_r|_{r=r_i} = -p_i \rightarrow$  gives A, C.

$$\Rightarrow \sigma_{r/\theta} = \pm \left[ \frac{r_i^2 r_0^2 (p_0 - p_i)}{r_0^2 - r_i^2} \right] \frac{1}{r^2} + \left[ \frac{p_i r_i^2 - p_0 r_0^2}{r_0^2 - r_i^2} \right] \rightarrow C$$



IIT Bombay



IIT Bombay

- $\sigma_r/\theta$  independent of  $E, \nu$
- $\epsilon_\theta = \frac{u_r}{r} + \frac{1}{r} u_{\theta,\theta}^0 \neq 0$  despite  $u_\theta = 0$   
 $\therefore u_r \neq 0$ .
- $\epsilon_z = -\frac{\nu}{E} (\sigma_r + \sigma_\theta) \xrightarrow[\text{const}]{\text{const}} \text{const} \Rightarrow \text{sections } \perp^{\text{ar}} \text{ to } z\text{-axis remain plane.}$
- If  $P_0 = 0 \rightarrow \sigma_r < 0$  (compr),  $\sigma_\theta > 0$  (tensile)

$$(\sigma_\theta)_{\max} = (\sigma_\theta)_{r=r_i} = P_i \frac{r_i^2 + r_o^2}{r_o^2 - r_i^2} > P_i \quad \left. \begin{array}{l} \text{So max} \\ \text{Shear} \\ \text{stress} \\ \text{at } r=r_i \end{array} \right\}$$

$$(\sigma_r)_{\min} = (\sigma_r)_{r=r_i} = -P_i \quad \text{---, ---}$$

$$\bullet \text{Thin walled} \rightarrow r_o - r_i = t, r_o + r_i = 2r \approx 2r_o \approx 2r_i \quad \left. \begin{array}{l} = \sigma_\theta - \sigma_r \\ \frac{1}{2} \end{array} \right\}$$

$$(P_0 = 0) \quad \sigma_\theta \approx \frac{P_i r}{t}, \sigma_r \approx 0$$

Same result from CE221 for closed  
t.w. cylinder, where additionally  $\sigma_2 = \frac{Pr}{2t}$

Case B: Ends uncapped but restrained  
i.e.  $\epsilon_{zz} = 0$ .

$$\sigma_{\theta z} = \sigma_{rz} = \epsilon_{\theta z} = \epsilon_{rz} = 0 \text{ as before.}$$

i.e., PLANE STRAIN.

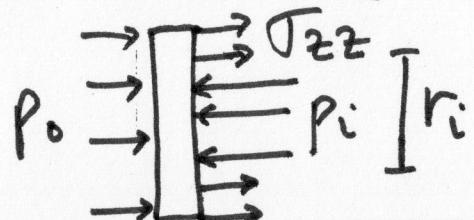
So results as before for stresses  $\sigma_r$ ,  $\sigma_\theta$

$$\sigma_{zz} = \nu(\sigma_r + \sigma_\theta) = 2\nu \frac{P_i r_i^2 - P_0 r_0^2}{r_0^2 - r_i^2} = \text{constant thru } r.$$

For displ's  $u_r$ ,  $u_\theta$ , put  $\nu \rightarrow \frac{\nu}{1-\nu}$ ,  $E \rightarrow \frac{E}{1-\nu^2}$  in previous expressions.

Case C: Ends capped, unrestrained

If caps are rigid disks, we expect  $\sigma_{zz} = \text{const}$  thru  $r$  at sections away from ends (St. Venant), as in Case B (but value of  $\sigma_{zz}$  changes).

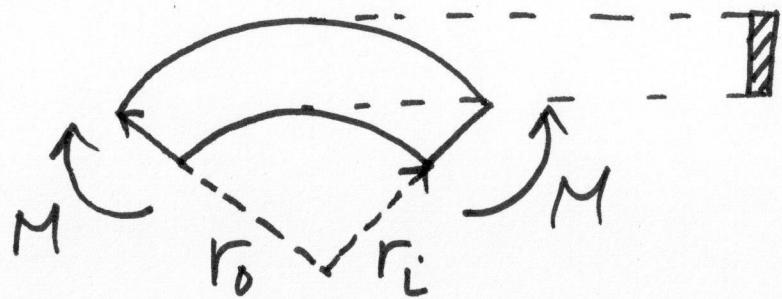


$$\Rightarrow \text{Equid} \rightarrow \sigma_{zz} = \frac{P_i r_i^2 - P_0 r_0^2}{r_0^2 - r_i^2}$$

$\sigma_r, \sigma_\theta \rightarrow$  as before.



## (II) Pure Bending of Curved Beam.



Beam in shape of circular arc with narrow rectangular section, loaded by end couples  
 $\Rightarrow M = \text{const} \neq M(\theta)$  (in-plane).  
 i.e axisymmetric problem.

BC's

$$\left. \sigma_r \right|_{\substack{r=r_0 \\ r=r_i}} = 0 \rightarrow \frac{A}{r_i^2} + B(1+2\ln r_i) + 2C = 0.$$

$$\frac{A}{r_0^2} + B(1+2\ln r_0) + 2C = 0$$

$\sigma_r \theta = 0$  on entire bndry  $\rightarrow$  i.s.

$$\int_{r_i}^{r_0} \sigma_\theta dr = 0 = \int_{r_i}^{r_0} \frac{d^2\phi}{dr^2} dr = \left. \frac{\partial \phi}{\partial r} \right|_{r_i}^{r_0} = r \sigma_r \Big|_{r_i}^{r_0} = 0 \quad (\text{due to } \sigma_r \Big|_{r=r_0} \text{ BC})$$

$\rightarrow$  if this BC satisfied.



IIT Bombay

$$\int_{r_i}^{r_0} \tau_\theta r dr = -M = \int \phi_{rr} r dr = \phi_r r \Big|_{r_i}^{r_0} - \phi \Big|_{r_i}^{r_0}$$

$$= \phi(r_i) - \phi(r_0)$$

$\left\{ \begin{array}{l} \sigma_r = 0 \\ \text{at } r_0, r_i \end{array} \right.$



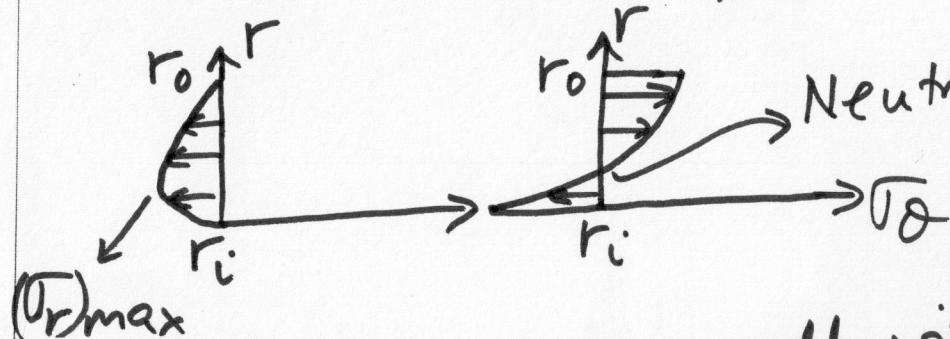
IIT Bombay

$$\Rightarrow M = A \ln \frac{r_0}{r_i} + B (r_0^2 \ln r_0 - r_i^2 \ln r_i) + C (r_0^2 - r_i^2)$$

Solve for  $A, B, C$ , result is,

$$\tau_r = -\frac{4M}{N} \left[ \frac{r_0^2 r_i^2}{r^2} \ln \frac{r_0}{r_i} + r_0^2 \ln \frac{r}{r_0} + r_i^2 \ln \frac{r_i}{r} \right]$$

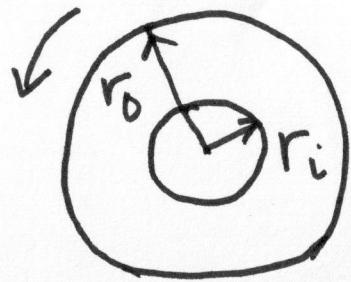
$$\tau_\theta = -\frac{4M}{N} \left[ -\frac{r_0^2 r_i^2}{r^2} \ln \frac{r_0}{r_i} + r_0^2 \ln \frac{r}{r_0} + r_i^2 \ln \frac{r_i}{r} + r_0^2 - r_i^2 \right]$$



Solution compares well with Solid Mech soln which assumes  
 $\tau_r = 0$  (ref. Timoshenko & Goodier p.74 table; Popov p.362-363  
 for Sol Mech soln).

Where,  
 $N = (r_0^2 - r_i^2)^2$   
 $-4r_0^2 r_i^2 \left( \ln \frac{r_0}{r_i} \right)^2$

### III Rotating Disk. (Displ. formulation).



Thin rotating disk.

$$\rightarrow \tau_{zz} = \tau_{rz} = \tau_{\theta z} = 0.$$

$$\text{Axisymmetry} \Rightarrow \frac{\partial}{\partial \theta} = 0.$$

Here  $\nabla^4 \phi \neq 0$  ( $\because$  B.F. nonzero). So we use displacement formulation using equil eqns.

$$\text{B.F.'s} \rightarrow B_r = f \omega^2 r ; B_\theta = f r \alpha$$

equil\_eqn  $\rightarrow \frac{d}{dr}(r \tau_r) - \tau_\theta + f \omega^2 r^2 = 0.$

$$\text{S.D. eqns} \rightarrow e_r = u_{r,r} ; e_\theta = u_r/r$$

$$\text{C.L. eqns} \rightarrow \tau_r = \frac{E}{1-\nu^2} (e_r + \nu e_\theta) = \frac{E}{1-\nu^2} \left( \frac{du_r}{dr} + \nu \frac{u_r}{r} \right)$$

$$\tau_\theta = \frac{E}{1-\nu^2} \left( \frac{u_r}{r} + \nu \frac{du_r}{dr} \right)$$

$$\text{subst in equil} \rightarrow r^2 u_r'' + r u_r' - u_r = -\frac{(1-\nu^2)}{E} f \omega^2 r^3$$



IIT Bombay

$$u_r = \frac{(u_r)_h}{r} + \cancel{\frac{(u_r)_p}{r}} \xrightarrow{\text{proportional to } r^3}$$

put  $r = e^t$

$$\ddot{u}_r - u_r = -\left(\frac{1-\nu^2}{E}\right) 8\omega^2 e^{3t}$$

$$(\cdot) = \frac{d}{dt}$$

$$u_r = \underbrace{C_1 e^t + C_2 e^{-t}}_{(u_r)_h} - \underbrace{\left(\frac{1-\nu^2}{E}\right) \frac{8\omega^2}{8} e^{3t}}_{(u_r)_p}$$

$$= C_1 r + \frac{C_2}{r} - \left(\frac{1-\nu^2}{E}\right) \frac{8\omega^2}{8} r^3$$

$$\sigma_r = \frac{E}{1-\nu^2} \left[ (1+\nu) C_1 - (1-\nu) \frac{C_2}{r^2} - (3+\nu) \frac{(1-\nu^2)}{8E} 8\omega^2 r^2 \right]$$

$$\tau_\theta = \frac{E}{1-\nu^2} \left[ (1+\nu) C_1 + (1-\nu) \frac{C_2}{r^2} - (1+3\nu) \frac{(1-\nu^2)}{8E} 8\omega^2 r^2 \right].$$

Solid Disk:  $r_i = 0$ ; finite stresses at  $r = 0 \rightarrow C_2 = 0$

$$(\sigma_r)_{r=r_0} = 0 \xrightarrow{\text{get}} C_1 \rightarrow \sigma_r = \left(\frac{3+8}{\nu}\right) 8\omega^2 (r_0^2 - r^2)$$

$$\tau_\theta = \left(\frac{3+\nu}{8}\right) 8\omega^2 r_0^2 - \left(\frac{1+3\nu}{8}\right) 8\omega^2 r^2$$



•  $\sigma_r, \sigma_\theta$  max at  $r=r_i=0$ ,  $(\sigma_r)_{max} = (\sigma_\theta)_{max} = \frac{3+\nu}{8} \rho w^2 r_0^2$

Disk with hole  $r_i \neq 0$

$\text{BC's} \rightarrow \left. \sigma_r \right|_{\substack{r=r_i \\ r=r_0}} = 0 \rightarrow \text{get } C_1, C_2$

$$\sigma_r = \frac{3+\nu}{8} \rho w^2 \left[ r_0^2 + r_i^2 - \frac{r_0^2 r_i^2}{r^2} - r^2 \right]$$

$$\sigma_\theta = \frac{3+\nu}{8} \rho w^2 \left[ r_0^2 + r_i^2 + \frac{r_0^2 r_i^2}{r^2} - \frac{1+3\nu}{3+\nu} r^2 \right]$$

Observations.

$$\left\{ \frac{d\sigma_r}{dr} = 0 \rightarrow (\sigma_r)_{max} = \frac{3+\nu}{8} \rho w^2 (r_0 - r_i)^2, \text{ at } r = \sqrt{r_0 r_i} \right.$$

$$(\sigma_\theta)_{max} = \frac{3+\nu}{4} \rho w^2 \left[ r_0^2 + \underbrace{\frac{1-\nu}{3+\nu} r_i^2}_{\because r_0^2 > (r_0 - r_i)^2} \right], \text{ at } r = r_i$$

$$(\sigma_\theta)_{max} > (\sigma_r)_{max}$$

$$r_i \rightarrow 0 \Rightarrow (\sigma_\theta)_{max} = \frac{3+\nu}{4} \rho w^2 r_0^2 = 2 * (\sigma_\theta)_{max}, \text{ disk w/o hole}$$

i.e., stress concentration



IIT Bombay

What about  $\theta$ -equil eqn ?.

$\theta$ -equil eqn :

$$\underbrace{\sigma_{r\theta,r} + 2\frac{\sigma_{r\theta}}{r} + \frac{\cancel{g_{\theta,\alpha}}}{r} + \cancel{B_\theta}}_{=0 \text{ for } (\sigma_{r\theta})_h} = 0$$



IIT Bombay

$$(\sigma_{r\theta})_h = C/r^2$$

$$(\sigma_{r\theta})_p = Kr^2 = -\frac{f\alpha}{4} r^2$$

$$\sigma_{r\theta} = \frac{C}{r^2} - \frac{f\alpha}{4} r^2$$

$$\text{BC: } \sigma_{r\theta}|_{r=r_0} = 0 \rightarrow \text{find } C \rightarrow \sigma_{r\theta} = \frac{f\alpha}{4} \left[ \frac{r_0^4}{r^2} - r^2 \right]$$

for  $\omega = \text{const}$ ,  $\alpha = 0$ ,  $\sigma_{r\theta} = 0$ .

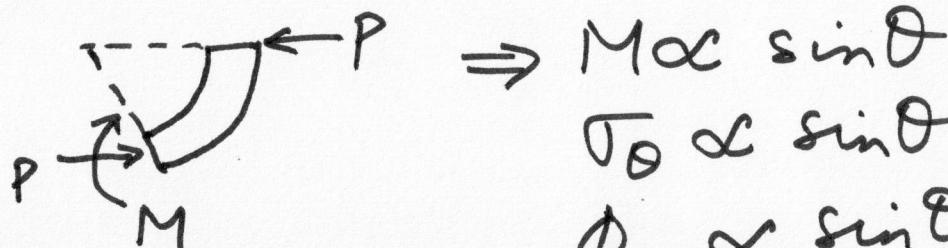
for  $\alpha \neq 0$ , torque  $T$  is applied thru stress distribution  $\sigma_{r\theta}|_{r=r_i}$

$$\Rightarrow T = \sigma_{r\theta}|_{r=r_i} \cdot 2\pi r_i \cdot \cancel{\frac{1}{2}} = \frac{f\alpha}{4} \cdot 2\pi \left[ \frac{r_0^4}{r_i^2} - r_i^2 \right]$$

unit thickness

# NON-AXISYMMETRIC PROBLEMS.

(I) END LOADED CURVED BEAM



Circular arc with narrow rectangular section.  
Force P in radial direction.

$$\rightarrow M \propto \sin \theta$$

$$r_0 \propto \sin \theta$$

$$\phi_{rr} \propto \sin \theta \rightarrow \text{try } \phi = f(r) \sin \theta.$$

$$\nabla^4 \phi = 0 \Rightarrow \left( \frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} - \frac{1}{r^2} \right) \left( \frac{d^2 \phi}{dr^2} + \frac{1}{r} \frac{df}{dr} - \frac{f}{r^2} \right) \sin \theta = 0$$

$$\Rightarrow f^{IV} - \frac{2}{r} f^{III} - \frac{3}{r^2} f^{II} + \frac{3}{r^3} f^I - \frac{3}{r^4} f = 0$$

$$r = e^t \Rightarrow \ddot{f} - 4\ddot{f} + 2\ddot{f} + 4\dot{f} - 3f = 0$$

$$f = A e^{3t} + B e^{-t} + C e^t + D t e^t$$

$$= A r^3 + \frac{B}{r} + C r + D r \ln r$$

$$(1) = \frac{d}{dt} \Rightarrow s^4 - 4s^3 + 2s^2 + 4s - 3 = 0$$

$$s = 3, -1, +1, +1$$



$$\sigma_r = \frac{\phi_{rr}}{r} + \frac{\phi_{r\theta\theta}}{r^2} = \left(2Ar - \frac{2B}{r^3} + \frac{D}{r}\right) \sin\theta$$

$$\sigma_\theta = \phi_{rrr} = \left(6Ar + \frac{2B}{r^3} + \frac{D}{r}\right) \sin\theta$$

$$\sigma_{r\theta} = -\frac{\partial}{\partial r} \left( \frac{1}{r} \phi_{r\theta} \right) = -\left(2Ar - \frac{2B}{r^3} + \frac{D}{r}\right) \cos\theta$$

BC's:  $\sigma_r \Big|_{\substack{r=r_0 \\ r=r_i}} = \sigma_{r\theta} \Big|_{\substack{r=r_0 \\ r=r_i}} = 0 \rightarrow$  yields only 2 indep eqns  
 $2Ar_i - \frac{2B}{r_i^3} + \frac{D}{r_i} = 0$

$$2Ar_0 - \frac{2B}{r_0^3} + \frac{D}{r_0} = 0$$

$$P = \int_{r_i}^{r_o} \sigma_{r\theta} \Big|_{\theta=0} dr = - \int_{r_i}^{r_o} \frac{\partial}{\partial r} \left( \frac{1}{r} \frac{\partial \phi}{\partial \theta} \right) \Big|_{\theta=0} dr = \frac{1}{r} \frac{\partial \phi}{\partial \theta} \Big|_{\substack{r=r_i \\ r=r_o}} \Big|_{\theta=0}$$

$$\Rightarrow P = -A(r_o^2 - r_i^2) + B \left( \frac{r_o^2 - r_i^2}{r_i^2 r_o^2} \right) - D \ln \frac{r_o}{r_i}$$

Solve for  $A, B, D$ ,  $A = \frac{P}{2N}$ ,  $B = -\frac{Pr_i^2 r_o^2}{2N}$ ,  $D = -\frac{P}{N} (r_i^2 + r_o^2)$ ,

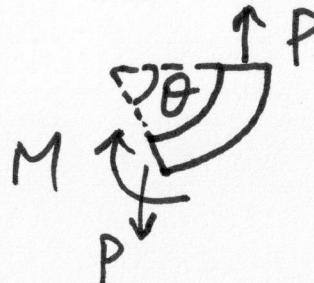
$$N = r_i^2 - r_o^2 + (r_i^2 + r_o^2) \ln \left( \frac{r_o}{r_i} \right)$$



IIT Bombay

Note:  $\tau_{\theta}|_{\theta=0} = 0$  is i.s.

- For vertical load  $P$ ,  $M = P\bar{r} - P\bar{r}\cos\theta$



use solution  
due to pure bending  
(axisymmetric)

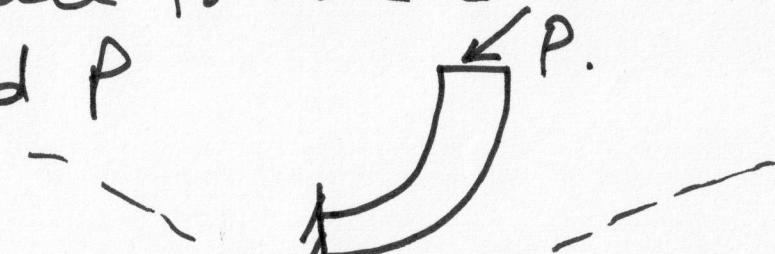
$$\bar{r} = \frac{r_o + r_i}{2}$$

use

$$\phi = f(r)\cos\theta$$

and proceed similarly.

- Then combine solutions due to horz & vert loads to get soln for inclined  $P$ .



- These solutions can also be used when loading on curved faces are non-zero, i.e.  $(\tau_r, \tau_\theta) \propto \sin\theta$  or  $\cos\theta$



IIT Bombay

## (II) Plate with circular hole.

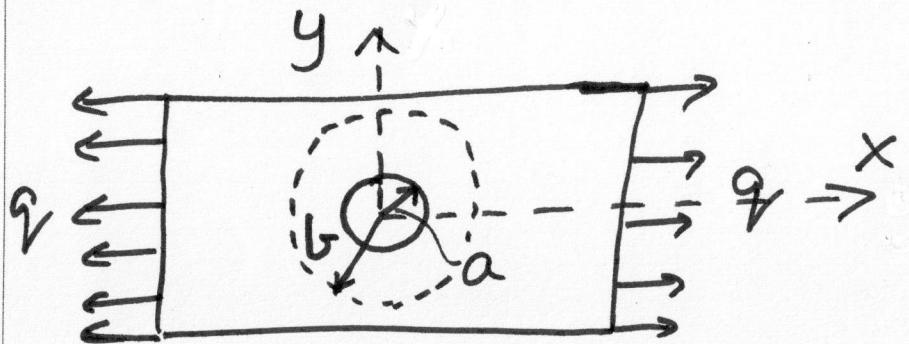


Plate uniformly loaded in  $x$ -dir.  
Fictitious boundary at  $r = b$ ,  $b \gg a$ ,  
 $a$  = hole radius.



IIT Bombay

$\therefore b \gg a$ ,  $\sigma_{xx}|_{r=b} = q$ ;  $\sigma_{yy}|_{r=b} = 0$ ;  $\sigma_{xy}|_{r=b} = 0 \rightarrow$  far field stresses

$$\text{Transformation} \Rightarrow \sigma_r|_{r=b} = \frac{q}{2} (1 + \cos 2\theta); \sigma_\theta|_{r=b} = \frac{q}{2} (1 - \cos 2\theta)$$

$$\tau_{r\theta}|_{r=b} = -\frac{q}{2} \sin 2\theta$$

So an equivalent problem is that of annular disk ( $r_i = a$ ,  $r_o = b$ ) loaded with  $\sigma_r|_{r=b}$  and  $\tau_{r\theta}|_{r=b}$  at outer boundary  $r = r_o = b$ . We solve this problem.

Part (A) soln : Due to Axisymmetric loading

$$\tau_r|_{r=b} = \frac{q}{2}$$

Put  $p_0 = -\frac{q}{2}$ ,  $p_i = 0$  in, <sup>soln. of</sup> Thick-walled cylinder  
with open (uncapped, unrestrained) ends. Use  
 $b \gg a$ , get,

$$\tau_r = \frac{q}{2} \left(1 - \frac{a^2}{r^2}\right); \quad \tau_\theta = \frac{q}{2} \left(1 + \frac{a^2}{r^2}\right); \quad \tau_{r\theta} = 0 \rightarrow$$

Part (B) soln :  $\tau_r|_{r=b} = \frac{q}{2} \cos 2\theta$ ,  $\tau_{r\theta}|_{r=b} = -\frac{q}{2} \sin 2\theta$  applied Part (A) soln

Semi-inverse method  $\rightarrow$  try  $\phi = f(r) \cos 2\theta \rightarrow$  gives  $\tau_r \propto \cos 2\theta$

$$\nabla^4 \phi = \left( \frac{d^2}{dr^2} + \frac{1}{r} \frac{d}{dr} - \frac{4}{r^2} \right) \left( \frac{d^2 f}{dr^2} + \frac{1}{r} \frac{df}{dr} - \frac{4f}{r^2} \right) \cos 2\theta = 0 \quad \frac{\tau_{r\theta}}{\tau_r} \propto \frac{\sin 2\theta}{\cos 2\theta}$$

$$\Rightarrow \left[ f^{IV} + \frac{2}{r} f^{III} - \frac{9}{r^2} f^{II} + \frac{9}{r^3} f^I \right] = 0$$

$$(I) = \frac{d}{dr} \quad \text{etc.}$$

$$r = e^t \Rightarrow f''' - 4f'' - 4f' + 16f = 0 \rightarrow s^4 - 4s^3 - 4s^2 + 16s = 0, \quad s=0, 2, -2, 4$$



IIT Bombay

$$f(r) = Ar^4 + Br^2 + C + \frac{D}{r^2}$$

$$\tau_r = -\cos 2\theta \left( 2B + \frac{4C}{r^2} + \frac{6D}{r^4} \right); \quad \tau_\theta = \cos 2\theta \left( 12Ar^2 + 2B + \frac{6D}{r^4} \right)$$

$$\tau_{r\theta} = \sin 2\theta \left( 6Ar^2 + 2B - \frac{2C}{r^2} - \frac{6D}{r^4} \right)$$

BC's:  $\tau_r|_{r=a} = 0 \rightarrow 2B + \frac{4C}{a^2} + \frac{6D}{a^4} = 0 \rightarrow (i)$

$$\tau_{r\theta}|_{r=a} = 0 \rightarrow 6Aa^2 + 2B - \frac{2C}{a^2} - \frac{6D}{a^4} = 0 \rightarrow (ii)$$

$$\tau_r|_{r=b} = \frac{q}{2} \cos 2\theta \rightarrow 2B + \frac{4C}{b^2} + \frac{6D}{b^4} = -\frac{q}{2} \rightarrow (iii)$$

$$\tau_{r\theta}|_{r=b} = -\frac{q}{2} \sin 2\theta \rightarrow 6Ab^2 + 2B - \frac{2C}{b^2} - \frac{6D}{b^4} = -\frac{q}{2} \rightarrow (iv)$$

Solve using  $\frac{a}{b} \rightarrow 0$ ,  $B = -\frac{q}{4}$  (from (iii))  $\rightarrow 2Ba^4 + 4C\cancel{a^2} + 6D\cancel{a^4} = -\frac{q}{2}$   
 $A = 0$  (from (iv))  $\rightarrow 6Ab^2\cancel{a^4} + 2B\cancel{a^4} - 2C\cancel{a^2} - 6D\cancel{a^4} = -\frac{q}{2}$   
 $C = \frac{qa^2}{2}, D = -\frac{q}{4}\frac{a^4}{2}$  (from (i), (iii)).



IIT Bombay

Combining Part (A) & Part (B) soln,

$$\sigma_r = \frac{q}{2} \left(1 - \frac{a^2}{r^2}\right) + \frac{q}{2} \cos 2\theta \left(1 - \frac{a^2}{r^2}\right) \left(1 - \frac{3a^2}{r^2}\right)$$

$$\sigma_\theta = \frac{q}{2} \left(1 + \frac{a^2}{r^2}\right) - \frac{q}{2} \cos 2\theta \left(1 + \frac{3a^2}{r^2}\right)$$

$$\sigma_{r\theta} = -\frac{q}{2} \sin 2\theta \left(1 - \frac{a^2}{r^2}\right) \left(1 + \frac{3a^2}{r^2}\right)$$

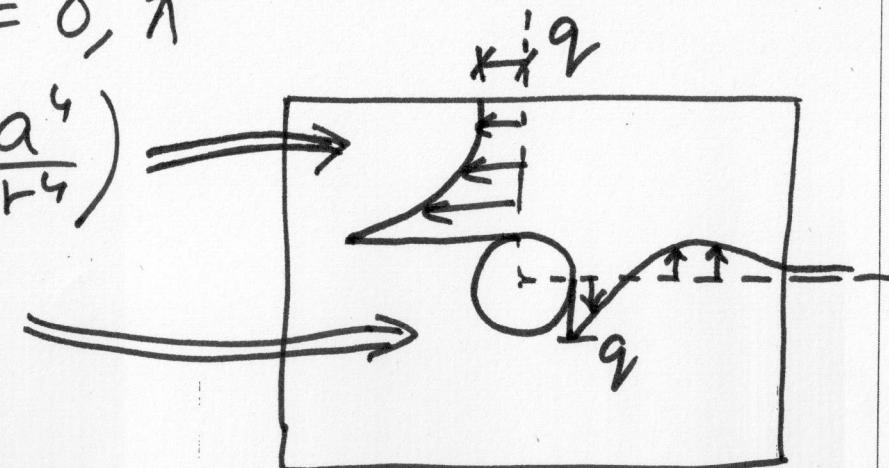
At  $r=a$ ,  $\sigma_r=0$ ,  $\sigma_\theta=q(1-2\cos 2\theta)$   
 $=3q$ ,  $\theta=\frac{\pi}{2}, \frac{3\pi}{2}$  → Stress concentration.  
 $=-q$ ,  $\theta=0, \pi$

At  $\theta=\frac{\pi}{2}$ ,  $\sigma_\theta=q\left(1+\frac{1}{2}\frac{a^2}{r^2}+\frac{3}{2}\frac{a^4}{r^4}\right)$

At  $\theta=0$ ,  $\sigma_\theta=-\frac{q}{2}\frac{a^2}{r^2}\left(\frac{3a^2}{r^2}-1\right)$



IIT Bombay



# If  $q$  acts in  $y$ -direction, use this solution  
with  $\theta \rightarrow \theta - \frac{\pi}{2}$ .

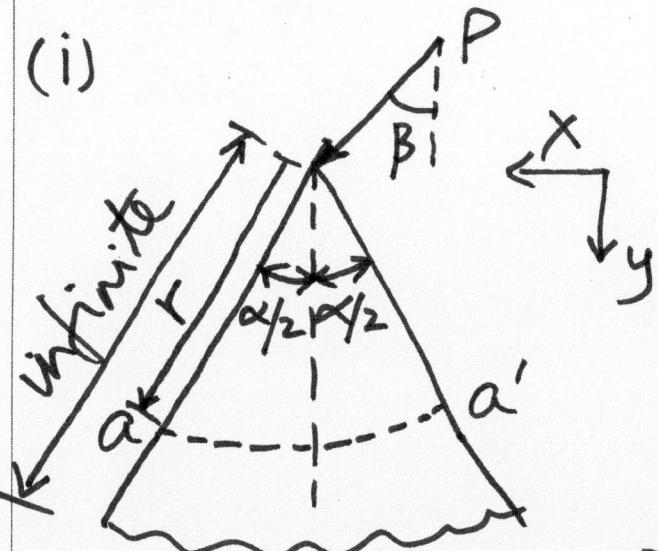
An approximate way to find stresses in a plate  
with multiple holes is as follows:

- (i) Find stresses in plate assuming no holes. — i.e far field stresses.
- (ii) Find principal stresses at the location of each hole,  
say  $q_1, q_2$  are p-stresses at a particular hole.
- (iii) Use  $q_1$  in solution derived &  $q_2$  with  $\theta \rightarrow \theta - \frac{\pi}{2}$  in soln  
derived & add results, to get stresses around  
(i.e in vicinity of hole).
- (iv) If holes are close to each other then the solutions in  
(iii) above will need to be superposed.



IIT Bombay

## Wedges.



Wedge angle =  $\alpha$ .

$P$  = concentrated load per unit thickness, ie N/m.

Stresses depend on  $P, \alpha, \beta_1, r, \theta$ .

Stresses =  $\frac{N}{m^2} = \frac{P}{r} \lambda$ ,  $\lambda$  = dimensionless function of  $\alpha, \beta_1, \theta$

⇒ From stress -  $\phi$  relation,

$$\boxed{\phi = r f(\theta)} \rightarrow f(\theta) \text{ contains } P, \lambda (\alpha, \beta_1, \theta)$$

$$\nabla^4 \phi = 0 = \frac{1}{r^3} \left[ \frac{d^4 f}{d\theta^4} + 2 \frac{d^2 f}{d\theta^2} + f \right] = 0 \xrightarrow{f = e^{s\theta}} (S^2 + 1)^2 = 0, S = \pm i, \pm i$$

$$\Rightarrow f = A \cos \theta + B \sin \theta + C \cos \theta + D \sin \theta$$

$$\Rightarrow \sigma_r = \frac{2}{r} (P \cos \theta - C \sin \theta) ; \quad \sigma_\theta = 0 ; \quad \sigma_{r\theta} = 0$$

BCs:  $\sigma_\theta|_{\theta=\pm\frac{\alpha}{2}} = 0 ; \quad \sigma_{r\theta}|_{\theta=\pm\frac{\alpha}{2}} = 0 \rightarrow \underline{\text{l.s.}}$



IIT Bombay

Use lump sum eqn to find C, D, by taking section at aa' at radial coord r.



IIT Bombay

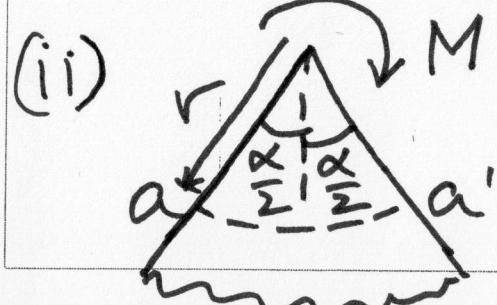
$$\int_{-\alpha/2}^{\alpha/2} \tau_r r d\theta \cos \theta + P \cos \beta = 0 \quad \{ \sum F_y = 0 \}$$

$$\int_{-\alpha/2}^{\alpha/2} \tau_r r d\theta \sin \theta + P \sin \beta = 0 \quad \{ \sum F_x = 0 \}$$

$$D(\sin \alpha + \alpha) + P \cos \beta = 0 \quad \} \text{ Solve for } C, D.$$

$$C(\sin \alpha - \alpha) + P \sin \beta = 0$$

$$\Rightarrow \boxed{\tau_r = -\frac{2P}{r} \left[ \frac{\cos \beta \cos \theta}{\alpha + \sin \alpha} + \frac{\sin \beta \sin \theta}{\alpha - \sin \alpha} \right]; \tau_0 = \tau_{r0} = 0}$$



M = Concentrated torque per unit thk,  $\frac{\text{Nm}}{\text{m}}$ .  
Stresses depend on M,  $\alpha$ , r,  $\theta$

$$\text{Stresses} \equiv \frac{N}{m^2} = \frac{M}{r^2} \lambda, \quad \lambda = \text{dimensionless f. n. of } \alpha, \theta.$$

From stress -  $\phi$  rel.  $\rightarrow \phi = f(\theta)$

$$\nabla^4 \phi = 0 \rightarrow \frac{1}{r^4} \left( \frac{\partial^4 f}{\partial \theta^4} + 4 \frac{\partial^2 f}{\partial \theta^2} \right) = 0 \rightarrow S = 0, 0, \pm 2i$$

$$\phi = f = A \cos 2\theta + B \sin 2\theta + C\theta + D$$

$$\tau_r = -\frac{1}{r^2} (A \cos 2\theta + B \sin 2\theta); \quad \tau_\theta = 0;$$

$$\tau_{r\theta} = \frac{1}{r^2} (-2A \sin 2\theta + 2B \cos 2\theta + C)$$

BC's:  $\tau_\theta|_{\theta=\pm\frac{\alpha}{2}} = 0 \rightarrow \underline{i.s.}$

$$\tau_{r\theta}|_{\theta=\pm\frac{\alpha}{2}} = 0 \Rightarrow A = 0 \quad \& \quad C = -2B \cos \alpha$$

Use lump sum equilibrium to get another relation between  
B & C.

$$\{\sum M = 0\} \rightarrow \int_{-\alpha/2}^{\alpha/2} \tau_{r\theta} r^2 d\theta + M = 0 \Rightarrow (2B \sin \alpha + C\alpha) \cancel{r^2} + M = 0$$



IIT Bombay

$$\tau_r = \frac{2M \sin 2\theta}{(\sin \alpha - \alpha \cos \alpha) r^2} ; \quad \tau_\theta = 0$$

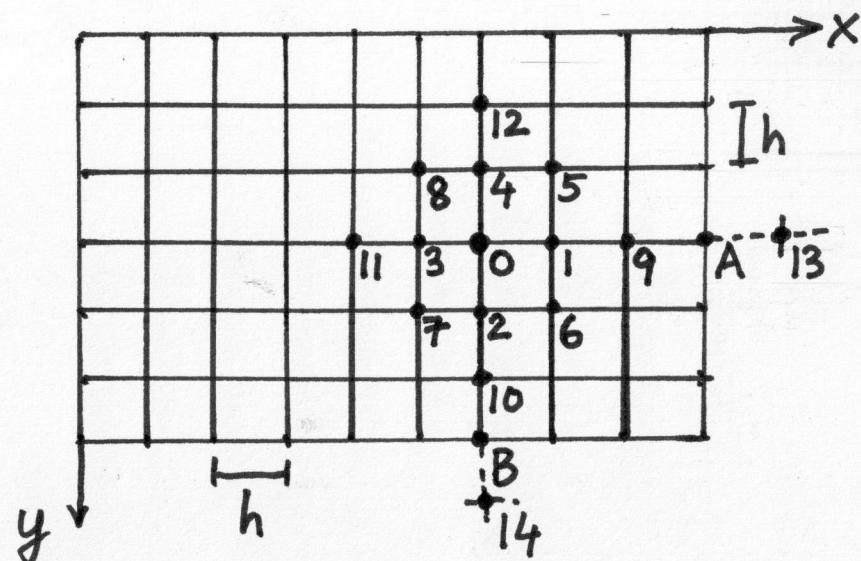
$$\tau_{r\theta} = \frac{M(\cos 2\theta - \cos \alpha)}{(\alpha \cos \alpha - \sin \alpha) r^2}$$

Note : You can verify that lumpsum  $\sum F_x = 0$ ,  $\sum F_y = 0$ , are i.s.



IIT Bombay

# FINITE DIFFERENCE METHOD FOR PLANE PROBLEMS



IIT Bombay

$$f_1 = f_0 + h \left( \frac{\partial f}{\partial x} \right)_0 + \frac{h^2}{2} \left( \frac{\partial^2 f}{\partial x^2} \right)_0 + \dots \rightarrow ①$$

$$f_3 = f_0 - h \left( \frac{\partial f}{\partial x} \right)_0 + \frac{h^2}{2} \left( \frac{\partial^2 f}{\partial x^2} \right)_0 + \dots \rightarrow ②$$

$$①, ② \rightarrow \left( \frac{\partial f}{\partial x} \right)_0 = \frac{f_1 - f_3}{2h} \rightarrow ③ ; \left( \frac{\partial^2 f}{\partial x^2} \right)_0 = \frac{f_1 + f_3 - 2f_0}{h^2} \rightarrow ④$$

$$\text{Similarly in } y\text{-dir} \rightarrow \left( \frac{\partial f}{\partial y} \right)_0 = \frac{f_2 - f_4}{2h} \rightarrow ③a ; \left( \frac{\partial^2 f}{\partial y^2} \right)_0 = \frac{f_2 + f_4 - 2f_0}{h^2} \rightarrow ④a$$

$$\left( \frac{\partial^2 f}{\partial x \partial y} \right)_0 = \left[ \frac{\partial}{\partial y} \left( \frac{\partial f}{\partial x} \right) \right]_0 = \frac{\left( \frac{\partial f}{\partial x} \right)_2 - \left( \frac{\partial f}{\partial x} \right)_4}{2h} = \frac{\frac{f_6 - f_7}{2h} - \frac{f_5 - f_8}{2h}}{2h} = \frac{f_6 + f_8 - f_5 - f_7}{4h^2}$$



IIT Bombay

Similarly,

$$\left(\frac{\partial^4 f}{\partial x^4}\right)_0 = \frac{1}{h^4} [6f_0 - 4(f_1 + f_3) + (f_9 + f_{11})] \rightarrow (5a)$$

$$\left(\frac{\partial^4 f}{\partial x^2 \partial y^2}\right)_0 = \frac{1}{h^4} [4f_0 - 2(f_1 + f_2 + f_3 + f_4) + (f_5 + f_6 + f_7 + f_8)] \rightarrow (5c)$$

$$\left(\frac{\partial^4 f}{\partial y^4}\right)_0 = \frac{1}{h^4} [6f_0 - 4(f_2 + f_4) + (f_{10} + f_{12})] \rightarrow (5b)$$

[③-⑤ are Central difference formulae. More accurate than forward/backward diff. formulae (done next).]

$$f_9 = f_0 + 2h \left(\frac{\partial f}{\partial x}\right)_0 + 2h^2 \left(\frac{\partial^2 f}{\partial x^2}\right)_0 + \dots \rightarrow 1a$$

$$①, 1a \rightarrow \left(\frac{\partial f}{\partial x}\right)_0 = \frac{-3f_0 + 4f_1 - f_2}{2h} \rightarrow ⑥; \quad \left(\frac{\partial^2 f}{\partial x^2}\right)_0 = \frac{f_0 - 2f_1 + f_2}{h^2} \rightarrow ⑦$$

$$\text{Similarly, } \left(\frac{\partial f}{\partial y}\right)_0 = \frac{-3f_0 + 4f_2 - f_{10}}{2h} \rightarrow 6a; \quad \left(\frac{\partial^2 f}{\partial y^2}\right)_0 = \frac{f_0 - 2f_2 + f_{10}}{h^2} \rightarrow 7a$$

Similarly, using  $f_{11} = f_0 - 2h \left( \frac{\partial f}{\partial x} \right)_0 + 2h^2 \left( \frac{\partial^2 f}{\partial x^2} \right)_0 + \dots$

$$②, ②a \rightarrow \left( \frac{\partial f}{\partial x} \right)_0 = \frac{3f_0 - 4f_3 + f_{11}}{2h} \rightarrow ⑧ ;$$

$$\left( \frac{\partial^2 f}{\partial x^2} \right)_0 = \frac{f_0 - 2f_3 + f_{11}}{h^2} \rightarrow ⑨ ;$$

Similarly,  $\left( \frac{\partial f}{\partial y} \right)_0 = \frac{3f_0 - 4f_4 + f_{12}}{2h} \rightarrow ⑧a ; \left( \frac{\partial^2 f}{\partial y^2} \right)_0 = \frac{f_0 - 2f_4 + f_{12}}{h^2} \rightarrow ⑨a$

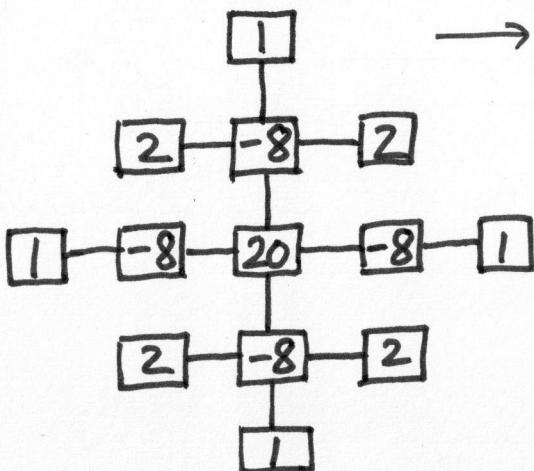
[ ⑥, ⑦ are Forward difference formulae ]  
 [ ⑧, ⑨ are Backward difference formulae ]

Use Forward/Backward diff formulae only for end-point  
 (boundary pt) derivatives : they are less accurate.

Thus,  $\nabla^4 \phi = 0 = 20\phi_0 - 8(\phi_1 + \phi_2 + \phi_3 + \phi_4) + 2(\phi_5 + \phi_6 + \phi_7 + \phi_8)$   
 $+ (\phi_9 + \phi_{10} + \phi_{11} + \phi_{12}) = 0 \rightarrow ⑩$



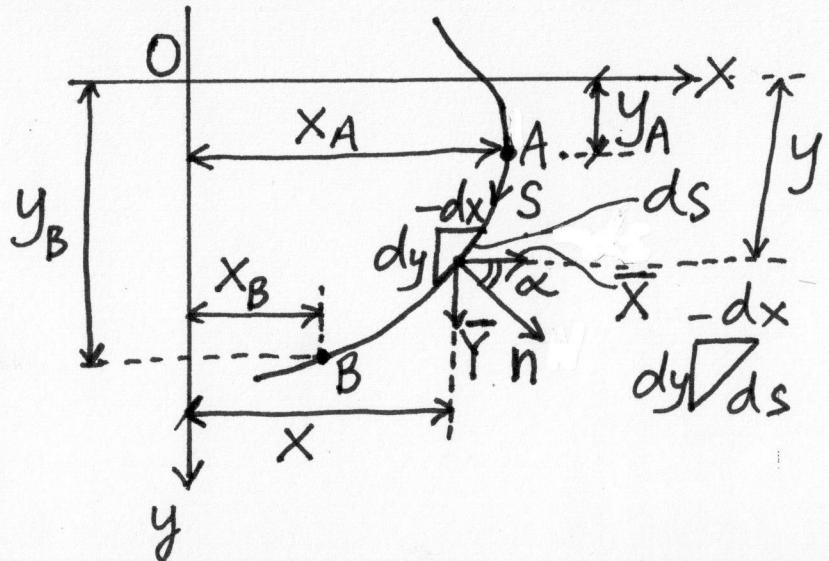
IIT Bombay



→ Eqn ⑩ in pictorial form.



Can write ⑩ for every interior point. However if point lies at distance 'h' from boundary, then fictitious nodes lying outside the domain boundary get involved (eg nodes 13, 14). So we do the following.



$$n = \{l, m\}^T$$

$$l = \cos \alpha = \frac{dy}{ds} ; m = \sin \alpha = -\frac{dx}{ds}$$

$$\text{Stress vector } \underline{t} = \bar{X} \underline{i} + \bar{Y} \underline{j} = \underline{\underline{\sigma}}_s \underline{n}$$

$$\bar{X} = l(\bar{\sigma}_{xx})_s + m(\bar{\sigma}_{xy})_s$$

$$\bar{Y} = l(\bar{\sigma}_{xy})_s + m(\bar{\sigma}_{yy})_s$$

$\underline{\underline{\sigma}}_s$  is stress vector on boundary S.

$$\left. \begin{aligned} \bar{X} &= \frac{dy}{ds} \left( \frac{\partial^2 \phi}{\partial y^2} \right)_S + \frac{dx}{ds} \left( \frac{\partial^2 \phi}{\partial x \partial y} \right)_S = \frac{d}{ds} \left( \frac{\partial \phi}{\partial y} \right)_S \\ \bar{Y} &= -\frac{dy}{ds} \left( \frac{\partial^2 \phi}{\partial x \partial y} \right)_S - \frac{dx}{ds} \left( \frac{\partial^2 \phi}{\partial x^2} \right)_S = -\frac{d}{ds} \left( \frac{\partial \phi}{\partial x} \right)_S \end{aligned} \right\} \rightarrow 11$$



IIT Bombay

Integrate wrt  $s$ , from  $A$  to  $B$ ,

$$\left( \frac{\partial \phi}{\partial y} \right)_B = \left( \frac{\partial \phi}{\partial y} \right)_A + \int_A^B \bar{X} ds ; \quad \left( \frac{\partial \phi}{\partial x} \right)_B = \left( \frac{\partial \phi}{\partial x} \right)_A - \int_A^B \bar{Y} ds \rightarrow 12$$

= 0 (see later)

"0 (see later).

$$\text{Also, } d\phi = \frac{\partial \phi}{\partial x} dx + \frac{\partial \phi}{\partial y} dy = \frac{\partial \phi}{\partial x} \frac{dx}{ds} ds + \frac{\partial \phi}{\partial y} \frac{dy}{ds} ds$$

$$\text{Integrate} \rightarrow \phi_B = \phi_A + \left( x \frac{\partial \phi}{\partial x} \right)_A^B - \int_A^B x \frac{d}{ds} \left( \frac{\partial \phi}{\partial x} \right) ds + \left( y \frac{\partial \phi}{\partial y} \right)_A^B - \int_A^B y \frac{d}{ds} \left( \frac{\partial \phi}{\partial y} \right) ds$$

Use 11 & 12  $\Rightarrow \phi_B = \phi_A + \underbrace{\left( x_B - x_A \right) \left( \frac{\partial \phi}{\partial x} \right)_A + \left( y_B - y_A \right) \left( \frac{\partial \phi}{\partial y} \right)_A}_{= 0 \text{ (see later)}} + \int_A^B (y_B - y) \bar{X} ds + \int_A^B (x - x_B) \bar{Y} ds$

Now we know that (constant + linear) terms in stress fn. don't affect stresses. So we can consider stress fn.  $(\phi + a + bx + cy)$  & solve for  $a, b, c$  from the 3 conditions  $\phi_A = \left(\frac{\partial \phi}{\partial x}\right)_A = \left(\frac{\partial \phi}{\partial y}\right)_A = 0$  without stresses being affected.

So w/o loss of generality take  $\phi_A = \left(\frac{\partial \phi}{\partial x}\right)_A = \left(\frac{\partial \phi}{\partial y}\right)_A = 0$  (analogous to choosing a datum in potential energy).

This works only for simply-connected domains.

The integrals in ⑫, ⑬ have following physical interpretation:

- Integral in ⑫, ⑬ represent sum of applied surface forces between pts A & B in x & y directions, respectively.
- Integrals in ⑬ represent sum of moments (tre CW) due to surface forces applied between A & B, moments <sup>being</sup> taken about B.



IIT Bombay

Value of  $\phi$  at fictitious (exterior) nodes are given by Central Difference formulae (3), (3a)

i.e,

$$\phi_{13} = \phi_9 + 2h \left( \frac{\partial \phi}{\partial x} \right)_A ; \quad \phi_{14} = \phi_{10} + 2h \left( \frac{\partial \phi}{\partial y} \right)_B \rightarrow 14$$



IIT Bombay

Summary:

Step ① Choose datum  $A_x$ , set  $\phi_A = \left( \frac{\partial \phi}{\partial x} \right)_A = \left( \frac{\partial \phi}{\partial y} \right)_A = 0$ . Calculate  $\phi_B, \left( \frac{\partial \phi}{\partial x} \right)_B, \left( \frac{\partial \phi}{\partial y} \right)_B$  for all boundary points using ⑫, ⑬ and physical interpretation of integrals appearing in ⑫, ⑬.

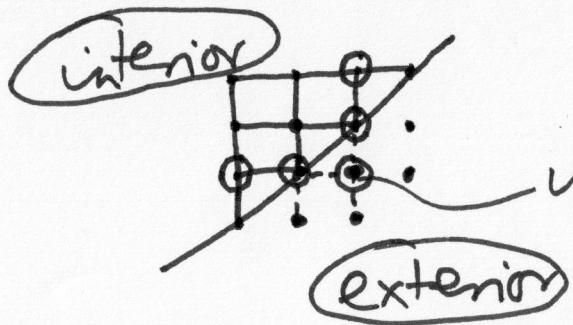
Step ② Express  $\phi$  at fictitious (exterior) nodes in terms of  $\phi$  at interior nodes using ⑭

Step ③ Formulate  $\nabla^4 \phi = 0$  at every interior node using ⑩

Step ④ Solve equations obtained in Step ② & Step ③ above for  $\phi$  at interior & fictitious (exterior) nodes.

Step ⑤ Find stress components using nodal  $\phi$ 's in eqns ④, ④a, ④b.

This procedure works if domain has horizontal & vertical boundaries. For inclined boundaries we will have to resort to forward/backward difference version of  $\nabla^4 \phi = 0$  (eqn ⑩) for nodes lying at distance 'h' from boundary ; and/or we will have to obtain  $\phi$  at fictitious nodes by averaging from x & y derivatives (ie averaging of eqn ⑯).

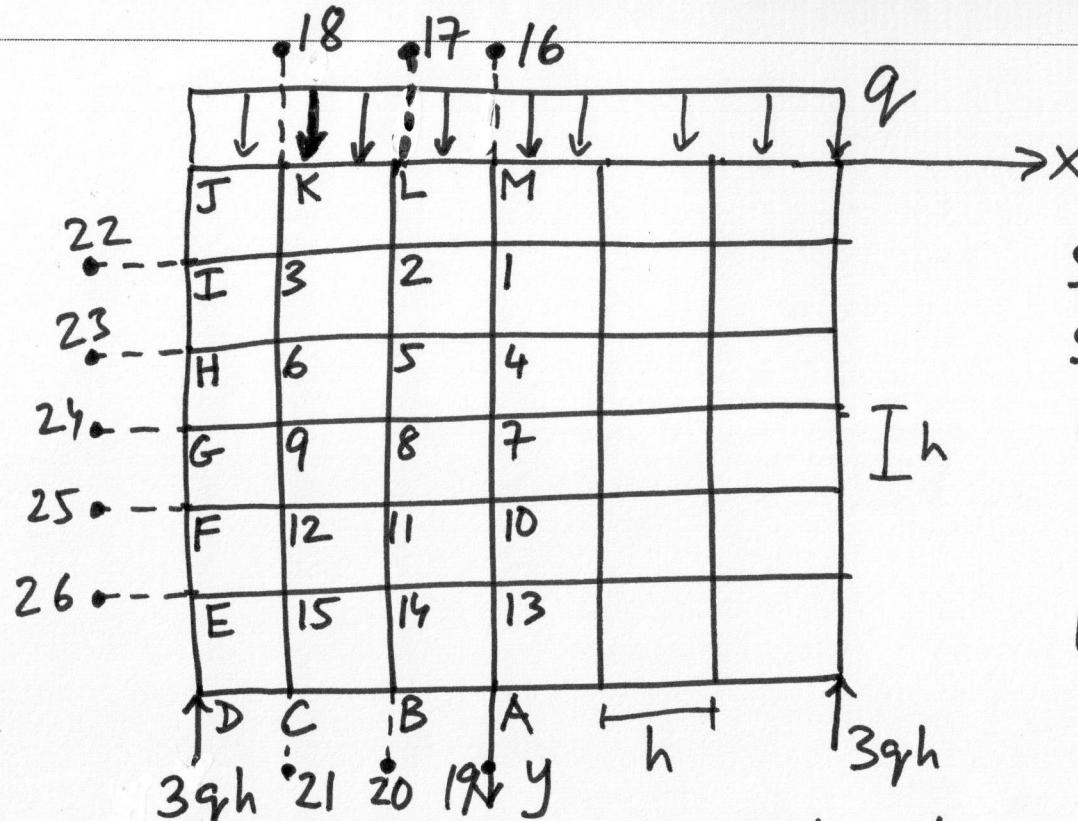


use averaged value of  $\phi$  obtained from x, y derivatives involving circled nodes.



IIT Bombay

Ex



Square beam  
size  $6h \times 6h$   
(ie deep beam)  
with  $udl = q$ .



Use symmetry, so analyze  
left half only.

Assume reactions concentrated at corners. This won't affect  
stresses much away from corners.

Step I Take datum point as A, ie  $\phi_A = \left(\frac{\partial \phi}{\partial x}\right)_A = \left(\frac{\partial \phi}{\partial y}\right)_A = 0$

Node	A	B, C	D	E, F, G, H, I	J	K	L	M
$\phi$	0	0	0	0	0	$2.5qh^2$	$4qh^2$	$4.5qh^2$
$\frac{\partial \phi}{\partial x}$	0	-	-	$3qh$	-	-	-	(-)
$\frac{\partial \phi}{\partial y}$	0	0	-	-	-	0	0	0

means not required  
in Eq (1)  
so not computed.

$$\left(\frac{\partial \phi}{\partial x}\right)_E = -\sum F_x \text{ surface loads between } A \& E = 0$$

$(\phi)_E = (\phi)_A + \sum \text{C.W. moments due to surface loads from } A \text{ to } E, \text{ taken about } E.$

$$(\phi)_L = (\phi)_A + (3gh)(2h) - (2hg)(h) = 4gh^2$$

Step II Express  $\phi$  at fictitious nodes (16-26) in terms of internal nodes, using Eq ⑭

$$\phi_{16} = \phi_1; \phi_{17} = \phi_2; \phi_{18} = \phi_3; \phi_{19} = \phi_{13}; \phi_{20} = \phi_{14}; \phi_{21} = \phi_{15}$$

$$\phi_{22} = \phi_3 - 2h \left( \frac{\partial \phi}{\partial x} \right)_I = \phi_3 - 6gh^2; \phi_{23} = \phi_6 - 6gh^2; \phi_{24} = \phi_9 - 6gh^2$$

$$\phi_{25} = \phi_{12} - 6gh^2; \phi_{26} = \phi_{15} - 6gh^2$$

Step III Formulate  $\nabla^4 \phi = 0$  for internal nodes (1-15), using Eq ⑩

$$20\phi_1 - 8(2\phi_2 + \phi_4 + \phi_{11}) + 2(2\phi_5 + 2\phi_L) + (2\phi_3 + \phi_7 + \phi_{16}) = 0$$

$\downarrow 4.5gh^2 \qquad \downarrow 4gh^2 \qquad \downarrow \phi_1$

$$\Rightarrow 21\phi_1 - 16\phi_2 + 2\phi_3 - 8\phi_4 + 4\phi_5 + \phi_7 - 20gh^2 = 0.$$

